Binary Heaps in Dynamic Arrays

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ITEE University of Queensland We have already learned that the binary heap serves as an efficient implementation of a priority queue. Our previous discussion was based on pointers (for getting a parent node connected with its children). In this lecture, we will see a "pointerless" way to implement a binary heap, which in practice achieves much lower space consumption.

We will also see a way to build a heap from n integers in just O(n) time, improving the obvious $O(n \log n)$ bound.

Recall:

Priority Queue

A priority queue stores a set S of n integers and supports the following operations:

- Insert(e): Adds a new integer to S.
- Delete-min: Removes the smallest integer in S, and returns it.

Recall:

Binary Heap

Let S be a set of n integers. A binary heap on S is a binary tree T satisfying:

- ① *T* is complete.
- 2 Every node u in T corresponds to a distinct integer in S—the integer is called the key of u (and is stored at u).
- If u is an internal node, the key of u is smaller than those of its child nodes.

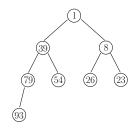
Storing a Complete Binary Tree Using an Array

Let T be any complete binary tree with n nodes. Let us linearize the nodes in the following manner:

- Put nodes at a higher level before those at a lower level.
- Within the same level, order the nodes from left to right.

Let us store the linearized sequence of nodes in an array A of length n.

Example



Stored as

1	39	8	79	54	26	23	93	
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Let us refer to the *i*-th element of A as A[i].

Lemma: Suppose that node u of T is stored at A[i]. Then, the left child of u is stored at A[2i], and the right child at A[2i+1].

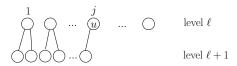
Observe this from the example of the previous slide.

Proof: Suppose that u is the j-th node at Level ℓ . This level must be full because u has a child node (which must be at Level $\ell+1$). In other words, there are 2^{ℓ} nodes at level ℓ .

We will prove the lemma only for the left child (the right child is simply stored at the next position of the array). From the fact that u is the i-th node in the linearized order, we know:

$$i = j + 2^{0} + 2^{1} + \dots + 2^{\ell-1}$$

= $j + 2^{\ell} - 1$.



Next we will prove that there are precisely i-1 nodes in A after u but before its left child. These nodes include:

- Those at Level ℓ behind u: there are $2^{\ell} i$ of them.
- Child nodes of the first j-1 nodes at Level ℓ : there are 2j of them.

Hence, in total, there are $2^{\ell}-j+2j=2^{\ell}+j=i-1$ such nodes. This completes the proof.



The following is an immediate corollary of the previous lemma:

Corollary: Suppose that node \underline{u} of T is stored at A[i]. Then, the parent of u is stored at A[|i/2|].

The following is a simple yet useful fact:

Lemma: The rightmost leaf node at the bottom level is stored at A[n].

Proof: Obvious.

Now we have got everything we need to implement the insertion and delete-min algorithms (discussed in the previous lecture) on the array representation of a binary heap.



Inserting 15:



Performing a delete-min:



Performance Guarantees

Combining our analysis on (i) binary heaps and (ii) dynamic arrays, we obtain the following guarantees on a binary heap implemented with a dynamic array:

- Space consumption O(n).
- Insertion: $O(\log n)$ time amortized.
- Delete-min: $O(\log n)$ time amortized.

Next, we consider the problem of creating a binary heap on a set S of n integers. Obviously, we can do so in $O(n \log n)$ time by doing n insertions. However, this is an overkill because the binary heap does not need to support any delete-min operations until all the n numbers have been inserted. This raises the question whether we can build the heap faster.

The answer is positive: we will see an algorithm that does so in O(n) time.

Fixing a Messed-Up Root

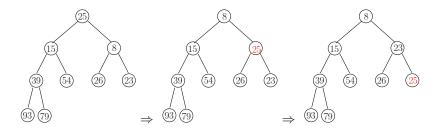
Let us first consider the following root-fix operation. We are given a complete binary tree T with root r. It is guaranteed that:

- The left subtree of r is a binary heap.
- The right subtree of *r* is a binary heap.

However, the key of r may not be smaller than the keys of its children. The operation fixes the issue, and makes T a binary heap.

This can be done in $O(\log n)$ time – in the same manner as the delete-min algorithm (by descending a path).

Example



Building a Heap

Given an array A that stores a set S of n integers, we can turn A into a binary heap on S using the following simple algorithm, which views A as a complete binary search tree T:

- For each i = n downto 1
 - Perform root-fix on the subtree of T rooted at A[i]

Think: Why are the conditions of root-fix always satisfied?

Example

							i				
54	26	15	93	8	1	23	39				
i											
54	26	15	93	8	1	23	39				
i											
54	26	15	93	8	1	23	39				
				i							
54	26	15	93	8	1	23	39				
i											
54	26	15	39	8	1	23	93				
i											
54	26	1	39	8	15	23	93				
	i										
54	8	1	39	26	15	23	93				
i											
1	8	15	39	26	54	23	93				

Running Time

Now let us analyze the time of the building algorithm. Suppose that T has height h. Without loss of generality, assume that all the levels of T are full – namely, $n=2^h-1$ (why no generality is lost?).

Observe:

- A node at Level h-1 incurs O(1) time in root-fix; 2^{h-1} such nodes.
- A node at Level h-2 incurs O(2) time in root-fix; 2^{h-2} such nodes.
- A node at Level h-3 incurs O(3) time in root-fix; 2^{h-3} such nodes.
- ...
- A node at Level h h incurs O(h) time in root-fix; 2^0 such nodes.



Running Time

Hence, the total time is bounded by

$$\sum_{i=1}^{h} O\left(i \cdot 2^{h-i}\right) = O\left(\sum_{i=1}^{h} i \cdot 2^{h-i}\right)$$

We will prove that the right hand side is O(n) in the next slide.

Running Time

Suppose that

$$x = 2^{h-1} + 2 \cdot 2^{h-2} + 3 \cdot 2^{h-3} + \dots + h \cdot 2^{0}$$
 (1)

$$\Rightarrow 2x = 2^{h} + 2 \cdot 2^{h-1} + 3 \cdot 2^{h-2} + \dots + h \cdot 2^{1}$$
 (2)

Subtracting (1) from (2) gives

$$x = 2^{h} + 2^{h-1} + 2^{h-2} + \dots + 2^{1} - h$$

$$\leq 2^{h+1}$$

$$= 2(n+1) = O(n).$$