

# The kd-Tree

## [Notes for the Training Camp]

Yufei Tao

ITEE  
University of Queensland

All our structures so far are “one-dimensional”, in the sense that each data element is an integer. In this talk, we will see our first two-dimensional data structure—named the **kd-tree**—for the classic problem of **range reporting**.

## Range Reporting

Let  $\mathbb{R}$  denote the set of real values. Let  $P$  be a set of  $n$  points in  $\mathbb{R}^2$  (namely, each point has the form  $(x, y)$  where  $x$  and  $y$  are real values).

Given an axis-parallel rectangle  $q$  (namely  $q$  has the form  $[x_1, x_2] \times [y_1, y_2]$ ), a **range reporting query** returns all the points of  $P$  that are covered by  $q$ .

Our objective is to store  $P$  in a data structure, so that we can answer all queries efficiently.

**Think:** How would you solve the range reporting problem in one-dimensional space?

The kd-tree that we will learn next solves the problem with  $O(n)$  space and  $O(\sqrt{n} + k)$  query time, where  $k$  is the number of points reported.

## kd-Tree

We will describe the structure in a recursive manner.

**Base Case:** If  $n = 0$ , the tree is empty. If  $n = 1$ , then the tree has a single node which stores the only point in  $P$ .

**General Case:**  $n \geq 2$ . Find a vertical line  $\ell_x$  that divides  $P$  as evenly as possible. Let  $P_{\text{left}}$  be the set of points of  $P$  on the left of  $\ell_x$ , and similar,  $P_{\text{right}}$  the set of points on the right.

Create a root node  $r$ , and store  $\ell_x$  at  $r$ .

If  $P_{\text{left}}$  has only 1 point, create a leaf node storing this point as the left child of  $r$ . Similarly, if  $P_{\text{right}}$  has only 1 point, create a leaf node storing this point as the right child of  $r$ .

Next, we consider that  $P_{\text{left}}$  and  $P_{\text{right}}$  have at least 2 points.

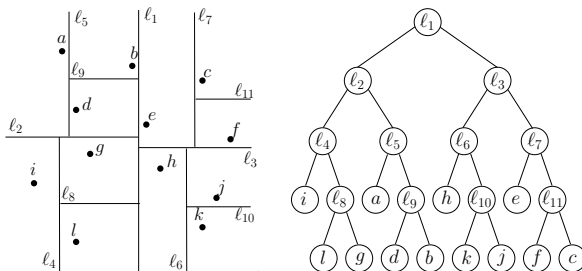
## kd-Tree

**General Case (cont.):** Find a horizontal line  $\ell_{y1}$  that divides  $P_{left}$  as evenly as possible into two sets  $P_1, P_2$ . Similarly, find a horizontal line  $\ell_{y2}$  that divides  $P_{right}$  as evenly as possible into two sets  $P_3, P_4$ .

Create a node  $u_1$  as the left child of  $r$ , and  $u_2$  as the right child of  $r$ . Store  $\ell_{y1}$  at  $u_1$ , and  $\ell_{y2}$  at  $u_2$ . Then comes the recursive construction:

- Create a kd-tree on  $P_1$ , and make its root the left child of  $u_1$ .
- Create a kd-tree on  $P_2$ , and make its root the right child of  $u_1$ .
- Create a kd-tree on  $P_3$ , and make its root the left child of  $u_2$ .
- Create a kd-tree on  $P_4$ , and make its root the right child of  $u_2$ .

## Example



Observe that **every node corresponds to a rectangle in the data space**. For example, the root corresponds to the entire data space. Its right child corresponds to the part of the data space on the right of  $\ell_1$ . The node  $\ell_6$  corresponds to the part that is to the right of  $\ell_1$ , and below  $\ell_3$ .

## Query

Given a node  $u$ , let  $R(u)$  be the rectangle in the data space that  $u$  corresponds to.

Given a query with rectangle  $q$ , we answer it as follows:

- Simply visit all the nodes  $u$  whose  $R(u)$  intersects  $q$ .
- At a leaf  $z$ , if the point  $p$  at  $z$  falls into  $q$ , report  $p$ .



The kd-tree clearly occupies  $O(n)$  space—noticing that every internal node of the kd-tree must have 2 children (why?), and that the tree has  $n$  leaves.

It is easy to construct the tree in  $O(n \log n)$  time (how?).

Next, we will prove that the query algorithm has running time  $O(\sqrt{n} + k)$ .

## Analysis

Given a vertical/horizontal line  $\ell$ , we say that  $\ell$  **intersects** a node  $u$  if  $\ell$  intersects  $R(u)$ .

The following is an important lemma behind the query efficiency:

**Lemma:** Any vertical line intersects  $O(\sqrt{n})$  nodes.

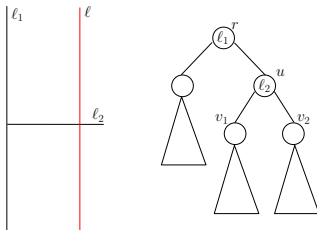
## Analysis

**Proof:** Denote by  $f(n)$  the largest number of nodes in a kd-tree of  $n$  points that can be intersected by any vertical line. Let us analyze what these nodes are.

First, the root  $r$  itself, whose rectangle is the whole universe, obviously intersects  $\ell$ . Let us assume, without loss of generality, that  $\ell$  is to the right of the split line at  $r$ . Let  $u$  be the right child of  $r$ . Clearly,  $\ell$  also intersects  $R(u)$ .

The next slide shows a figure about this.

## Analysis



How about the nodes in the subtrees rooted at  $v_1$  and  $v_2$ ? How many of them intersect  $\ell$ ? Observe that, each subtree is a kd-tree on at most  $n/4$  nodes! So the answer is at most  $f(n/4)$  per subtree!

## Analysis

Therefore, we have obtained an recurrence about  $f(n)$ :

$$f(n) \leq 2 + 2f(n/4).$$

The terminating condition is  $f(1) = 1$ .

Solving the recurrence gives  $f(n) = O(\sqrt{n})$

□.

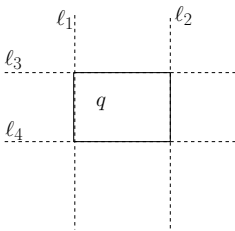
We can also prove that any horizontal line intersects the rectangles of  $O(\sqrt{n})$  nodes.

## Analysis

We are now ready for our grand theorem:

**Theorem:** The kd-tree answers a query in  $O(\sqrt{n} + k)$  time.

**Proof:** Let  $\ell_1, \ell_2, \ell_3, \ell_4$  be the vertical or horizontal lines defining the boundary of the query rectangle  $q$ , as shown below:



## Analysis

Recall that every node  $u$  visited by the query must have its  $R(u)$  intersecting  $q$ . We divide such nodes  $u$  into two categories:

- **Category 1:**  $R(u)$  intersects at least one edge of  $q$ .
- **Category 2:**  $R(u)$  falls completely **inside**  $q$ .

How many nodes are there in the first category? The answer is at most  $4\sqrt{n}$ —noticing that every node  $u$  of this category must have  $R(u)$  intersecting one of  $\ell_1, \ell_2, \ell_3$  and  $\ell_4$ !

So it remains to bound the number of nodes in Category 2. We will show that there are only  $O(k)$  of them. This will complete the proof that the query time is  $O(\sqrt{n} + k)$ .

## Analysis

Let  $v$  be a node in Category 2. Call  $v$  a **top node** if its parent is not in Category 2. Observe that:

- The subtrees of two top nodes must be disjoint (i.e., no top node can be a proper descendant of another).
- Every node in Category 2 must be in the subtree of a top node.
- Every leaf descendant of a top node must store a point falling in  $q$ .

Since the number of internal nodes in each subtree equals the number of leaves in that subtree minus 1, the above facts imply that Category 2 has  $O(k)$  nodes.  $\square$



We have seen range reporting in 1d space, and 2d space. The problem definition extends to any  $d$ -dimensional space, where  $d$  is an integer.

The kd-tree, too, can be extended! In  $d$ -dimensional space (where  $d = O(1)$  and  $d \geq 2$ ), it still uses  $O(n)$  space, and answers a query in  $O(n^{1-1/d} + k)$  time.

How?