# Basic Concepts of Graphs

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Basic Concepts of Graphs

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## Undirected Graphs

An **undirected graph** is a pair of (V, E) where:

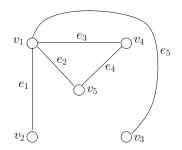
- V is a set of elements, each of which called a node.
- *E* is a set of **unordered pairs** {*u*, *v*} where *u* and *v* are nodes.

A node is also called a **vertex**. Each element  $\{u, v\} \in E$  is also called an **edge**. Node *u* is a **neighbor** of *v*; the two vertices are **adjacent** to each other.

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Image: A image: A





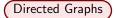
This is an undirected graph where there are 5 vertices  $v_1, v_2, ..., v_5$ , and 5 edges  $e_1, e_2, ..., e_5$ .

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#### An **directed graph** is a pair of (V, E) where:

- V is a set of elements, each of which called a **node**.
- E is a set of pairs (u, v) where u and v are nodes in V.

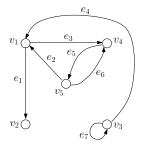
A node is also called a **vertex**. Each element  $\{u, v\} \in E$  is also called an **edge**.

Each element  $(u, v) \in E$  is a **directed edge**. More specifically, it is an **outgoing** edge of u and an **incoming** edge of v. Accordingly, v is an **out-neighbor** of u and u is an **in-neighbor** of v.

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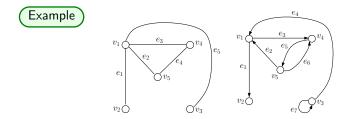
This is a directed graph (V, E) where there are 5 vertices  $v_1, v_2, ..., v_5$ , and 7 edges  $e_1, e_2, ..., e_7$ . Edge  $e_6$ , for instance, is an outgoing edge of  $v_5$ and an incoming edge of  $v_4$ .

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- In an undirected graph, the **degree** of a vertex *u* is the number of edges of *u*.
- In a directed graph, the **out-degree** of a vertex *u* is the number outgoing edges of *u*, and its **in-degree** is the number of its incoming edges.



In the left graph, the degree of  $v_5$  is 2. In the right graph, the out-degree of  $v_3$  is 2 and its in-degree is 1.

Image: A matrix and a matrix

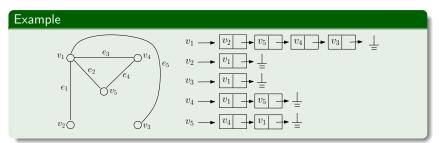
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Next, we discuss two common ways to store a graph: **adjacency list** and **adjacency matrix**. In both cases, we represent each vertex in V using a unique id in 1, 2, ..., |V|.

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## Adjacency List – Undirected Graphs

Each vertex  $u \in V$  is associated with a linked list that enumerates all the vertices adjacent to u.



Space = O(|V| + |E|).

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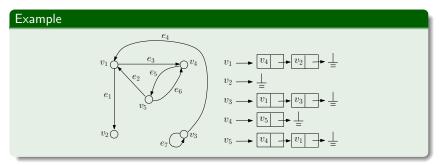
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# Adjacency List – Directed Graphs

Each vertex  $u \in V$  is associated with a linked list that enumerates all the out-neighbors of u.



Space = O(|V| + |E|).

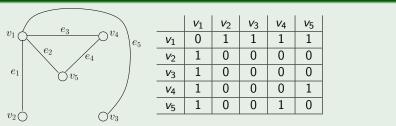
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Adjacency Matrix – Undirected Graphs

A  $|V| \times |V|$  matrix *A* where A[u, v] = 1 if  $(u, v) \in E$ , or 0 otherwise.

#### Example



- A must be symmetric.
- Space =  $O(|V|^2)$ .

Think: How to store A so that, for any vertices  $u, v \in V$ , we can find out if they have an edge in constant time?

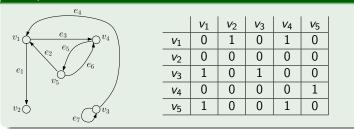
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## Adjacency Matrix – Directed Graphs

Defined in the same way as in the undirected case.

#### Example



- A may not be symmetric.
- Space =  $O(|V|^2)$ .

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