The kd-Tree [Notes for ESTR2102]

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All our structures so far are "one-dimensional", in the sense that each data element is an integer. In this talk, we will see our first two-dimensional data structure—named the kd-tree—for the classic problem of range reporting.



Let \mathbb{R} denote the set of real values. Let P be a set of n points in \mathbb{R}^2 (namely, each point has the form (x, y) where x and y are real values).

Given an axis-parallel rectangle q (namely q has the form $[x_1, x_2] \times [y_1, y_2]$), a range reporting query returns all the points of P that are covered by q.

Our objective is to store P in a data structure, so that we can answer all queries efficiently.

Think: How would you solve the range reporting problem in onedimensional space? The kd-tree that we will learn next solves the problem with O(n) space and $O(\sqrt{n} + k)$ query time, where k is the number of points reported.



We will describe the structure in a recursive manner.

Base Case: If n = 0, the tree is empty. If n = 1, then the tree has a single node which stores the only point in *P*.

General Case: $n \ge 2$. Find a vertical line ℓ_x that divides P as evenly as possible. Let P_{left} be the set of points of P on the left of ℓ_x , and similar, P_{right} the set of points on the right.

Create a root node r, and store ℓ_x at r.

If P_{left} has only 1 point, create a leaf node storing this point as the left child of r. Similarly, if P_{right} has only 1 point, create a leaf node storing this point as the right child of r.

Next, we consider that P_{left} and P_{right} have at least 2 points.

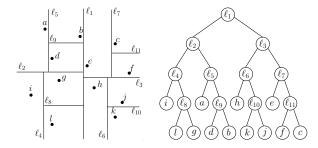


General Case (cont.): Find a horizontal line ℓ_{y1} that divides P_{left} as evenly as possible into two sets P_1, P_2 . Similarly, find a horizontal line ℓ_{y2} that divides P_{right} as evenly as possible into two sets P_3, P_4 .

Create a node u_1 as the left child of r, and u_2 as the right child of r. Store l_{y1} at u_1 , and l_{y2} at u_2 . Then comes the recursive construction:

- Create a kd-tree on P_1 , and make its root the left child of u_1 .
- Create a kd-tree on P_2 , and make its root the right child of u_1 .
- Create a kd-tree on P_3 , and make its root the left child of u_2 .
- Create a kd-tree on P_4 , and make its root the right child of u_2 .





Observe that every node corresponds to a rectangle in the data space. For example, the root corresponds to the entire data space. Its right child corresponds to the part of the data space on the right of ℓ_1 . The node l_6 corresponds to the part that is to the right of ℓ_1 , and below ℓ_3 .



Given a node u, let R(u) be the rectangle in the data space that u corresponds to.

Given a query with rectangle q, we answer it as follows:

- Simply visit all the nodes u whose R(u) intersects q.
- At a leaf z, if the point p at z falls into q, report p.

The kd-tree clearly occupies O(n) space—noticing that every internal node of the kd-tree must have 2 children (why?), and that the tree has n leaves.

It is easy to construct the tree in $O(n \log n)$ time (how?).

Next, we will prove that the query algorithm has running time $O(\sqrt{n}+k)$.

Analysis

Given a vertical/horizontal line ℓ , we say that ℓ intersects a node u if ℓ intersects R(u).

The following is an important lemma behind the query efficiency:

Lemma: Any vertical line intersects $O(\sqrt{n})$ nodes.

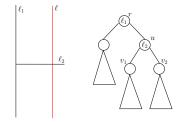
Analysis

Proof: Denote by f(n) the largest number of nodes in a kd-tree of n points that can be intersected by any vertical line. Let us analyze what these nodes are.

First, the root r itself, whose rectangle is the whole universe, obviously intersects ℓ . Let us assume, without loss of generality, that ℓ is to the right of the split line at r. Let u be the right child of r. Clearly, ℓ also intersects R(u).

The next slide shows a figure about this.





How about the nodes in the subtrees rooted at v_1 and v_2 ? How many of them intersect ℓ ? Observe that, each subtree is a kd-tree on at most n/4 nodes! So the answer is at most f(n/4) per subtree!



Therefore, we have obtained an recurrence about f(n):

$$f(n) \leq 2+2f(n/4).$$

The terminating condition is f(1) = 1.

Solving the recurrence gives $f(n) = O(\sqrt{n})$

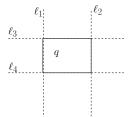
We can also prove that any horizontal line intersects the rectangles of $O(\sqrt{n})$ noes.



We are now ready for our grand theorem:

Theorem: The kd-tree answers a query in $O(\sqrt{n} + k)$ time.

Proof: Let $\ell_1, \ell_2, \ell_3, \ell_4$ be the vertical or horizontal lines defining the boundary of the query rectangle q, as shown below:



Analysis

Recall that every node u visited by the query must have its R(u) intersecting q. We divide such nodes u into two categories:

- Category 1: R(u) intersects at least one edge of q.
- **Category 2:** R(u) falls completely inside q.

How many nodes are there in the first category? The answer is at most $4\sqrt{n}$ —noticing that every node u of this category must have R(u) intersecting one of ℓ_1, ℓ_2, ℓ_3 and ℓ_4 !

So it remains to bound the number of nodes in Category 2. We will show that there are only O(k) of them. This will complete the proof that the query time is $O(\sqrt{n} + k)$.

Analysis

Let v be a node in Category 2. Call v a top node if its parent is not in Category 2. Observe that:

- The subtrees of two top nodes must be disjoint (i.e., no top node can be a proper descendant of another).
- Every node in Category 2 must be in the subtree of a top node.
- Every leaf descendant of a top node must store a point falling in q.

Since the number of internal nodes in each subtree equals the number of leaves in that subtree minus 1, the above facts imply that Category 2 has O(k) nodes.

We have seen range reporting in 1d space, and 2d space. The problem definition extends to any d-dimensional space, where d is an integer.

The kd-tree, too, can be extended! In *d*-dimensional space (where d = O(1) and $d \ge 2$), it still uses O(n) space, and answers a query in $O(n^{1-1/d} + k)$ time.

How?