



Department of Computer Science and Engineering The Chinese University of Hong Kong REAL-MUNICATION APPROVE TO TRANSPORT

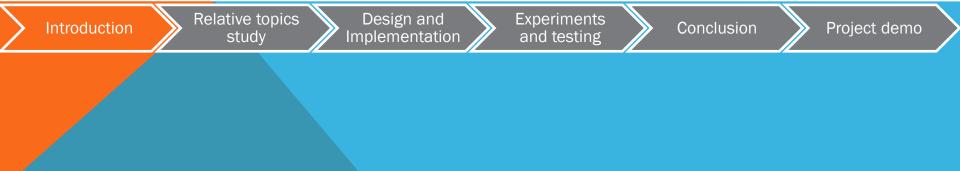
Supervisor: Prof. LYU Rung Tsong Michael

Students: LUO Xin (1155026046) ZOU Lei (1155026057)

AGENDA

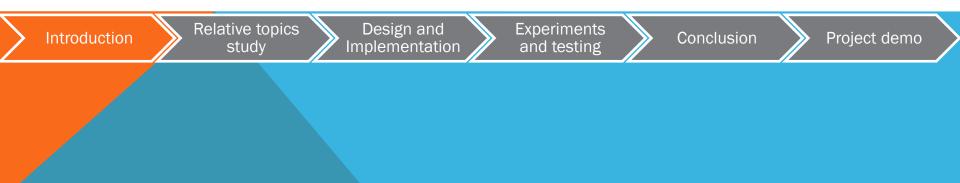
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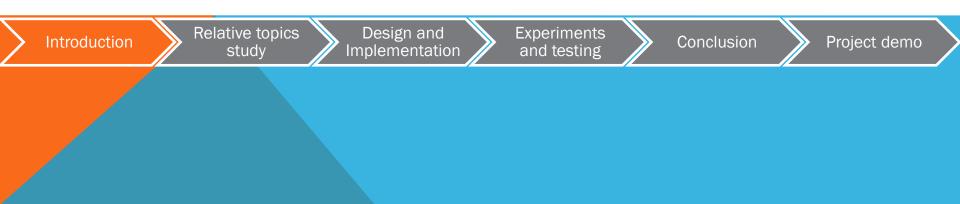
MOTIVATION





OBJECTIVES

- Encoding Morse code and playing it by flashlight;
- Decoding Morse code of light pattern;
- Allowing users to change transmission rates;
- Decoding messages with any transmission rate in some range;
- Bi-directional communication in the standard way;
- Template database in case of emergency, for example, SOS;
- Saving words or sentences used frequently to the template database.

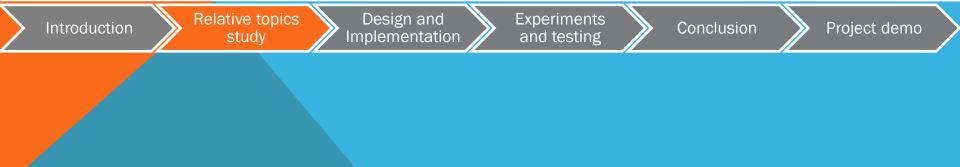


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Introduction

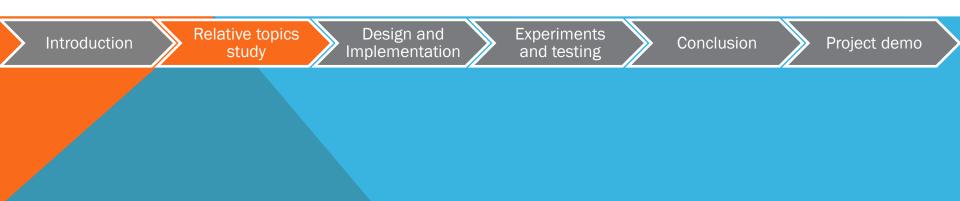
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INTRODUCTION TO MORSE CODE

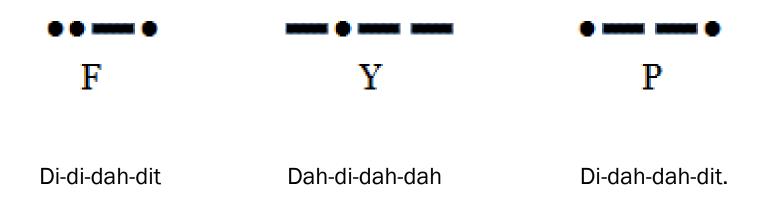
Coding rule

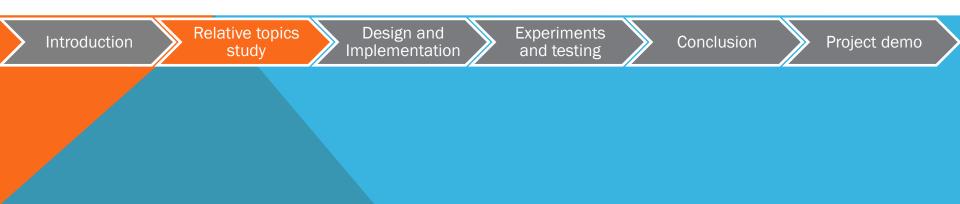
Element	Time
Dot (•)	1 time unit
Dash (🚥)	3 time units
Inter-element gap	1 time unit
Short gap between letters	3 time units
Medium gap between words	7 time units



INTRODUCTION OF MORSE CODE

Example:







In the past

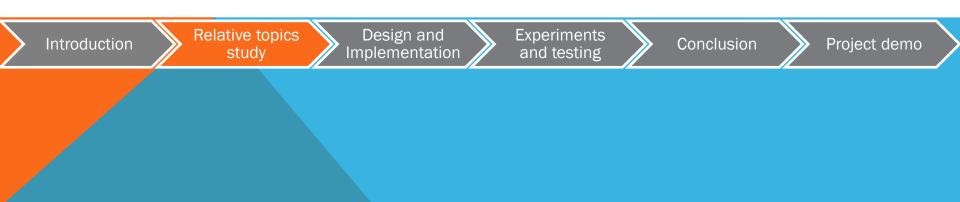
Human eyes to see things

Image processed in our brain

Now

Machine eyes to see things

Real time image processed in machine



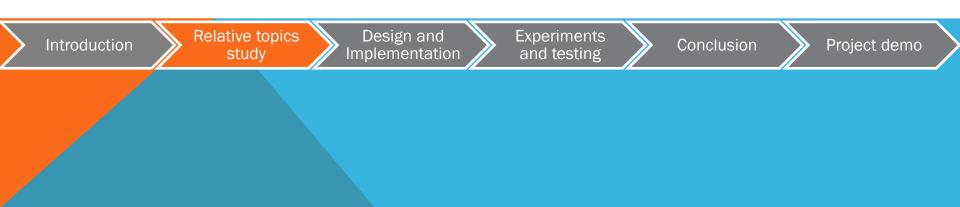


Open source library

- Computer Vision algorithms
- Machine learning algorithms

Usage

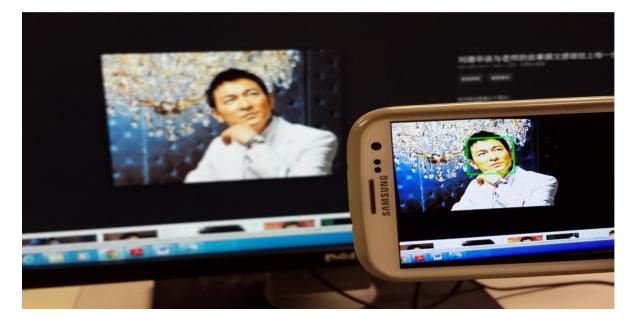
- Face detection
- Camera's movements trace
- Human actions' classification
- •••••

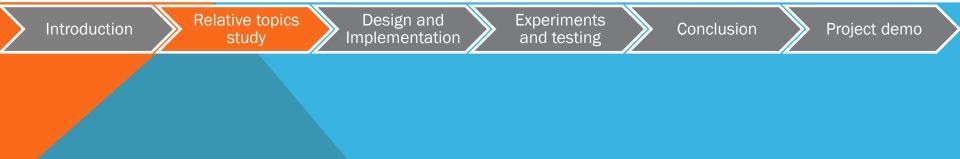




Simple Android application

Face Detection

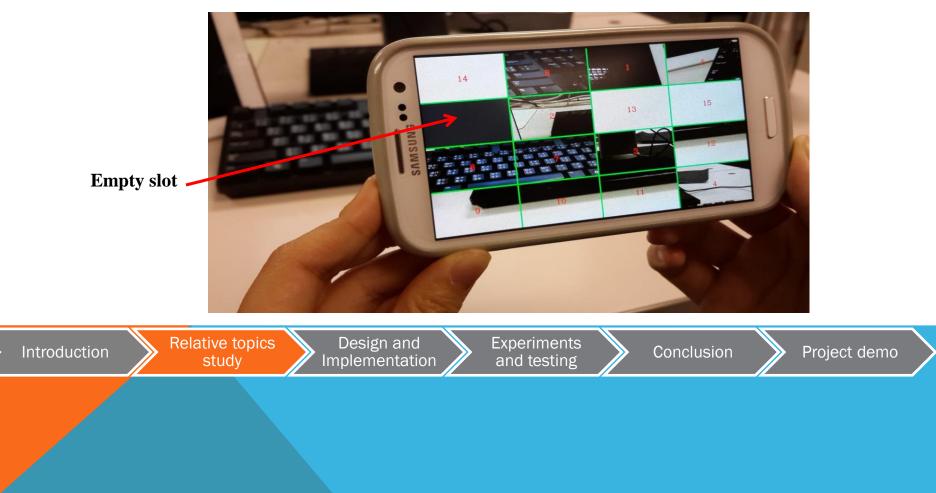






Simple Android application

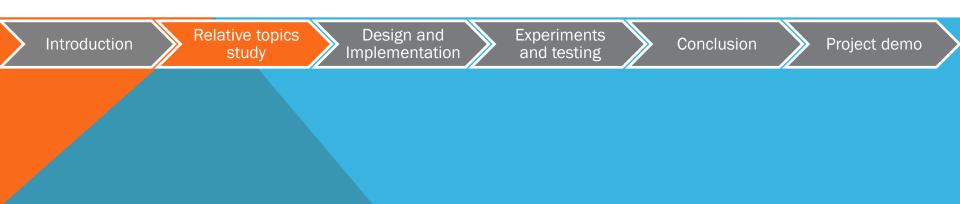
Puzzle game





OpenCV and our App

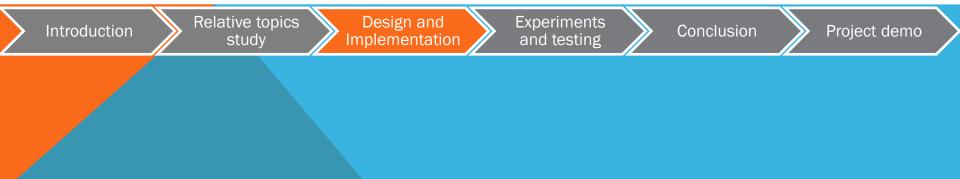
- Detection part mainly depends on OpenCV
- Real time image
- High speed image processing

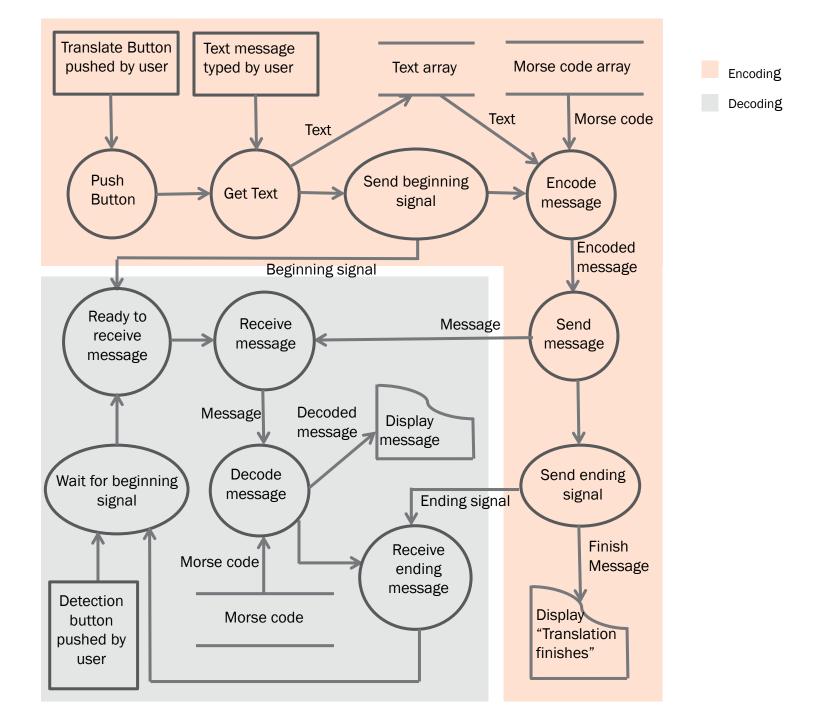


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ENCODING

Index	Code[index]	Correspon- ding symbol	Index	Code[index]	Correspon- ding symbol
0	{1, 3}	A/a	27	{1, 3, 3, 3, 3}	1
1	{3, 1, 1, 1}	B/b	28	{1, 1, 3, 3, 3}	2
2	{3, 1, 3, 1}	C/c	29	{1, 1, 1, 3, 3}	3
3	{3, 1, 1}	D/d	30	{1, 1, 1, 1, 3}	4
4	{1}	E/e	31	{1, 1, 1, 1, 1}	5
5	{1, 1, 3, 1}	F/f	32	{3, 1, 1, 1, 1}	6
6	{3, 3, 1}	G/g	33	{3, 3, 1, 1, 1}	7
7	$\{1, 1, 1, 1\}$	H/h	34	{3, 3, 3, 1, 1}	8
8	{1, 1}	l/i	35	{3, 3, 3, 3, 1}	9
9	{1, 3, 3, 3}	J/j	36	{1, 3, 1, 3, 1, 3}	
10	{3, 1, 3}	K/k	37	{3, 3, 1, 1, 3, 3}	,
11	$\{1, 3, 1, 1\}$	L/I	38	{1, 1, 3, 3, 1, 1}	?
12	{3, 3}	M/m	39	{1, 3, 3, 3, 3, 1}	,
13	{3, 1}	N/n	40	{3, 1, 3, 1, 3, 3}	!
14	{3, 3, 3}	0/0	41	{3, 1, 1, 3, 1}	/
15	{1, 3, 3, 1}	P/p	42	{3, 1, 3, 3, 1}	(
16	{3, 3, 1, 3}	Q/q	43	{3, 1, 3, 3, 1, 3})
17	{1, 3, 1}	R/r	44	{1, 3, 1, 1, 1}	&
18	{1, 1, 1}	S/s	45	{3, 3, 3, 1, 1, 1}	:
19	{3}	T/t	46	{3, 1, 3, 1, 3, 1}	;
20	{1, 1, 3}	U/u	47	{3, 1, 1, 1, 3}	=
21	{1, 1, 1, 3}	V/v	48	{1, 3, 1, 3, 1}	+
22	{1, 3, 3}	W/w	49	{3, 1, 1, 1, 1, 3}	-
23	{3, 1, 1, 3}	X/x	50	{1, 1, 3, 3, 1, 3}	_
24	{3, 1, 3, 3}	Y/y	51	{1, 3, 1, 1, 3, 1}	"
25	{3, 3, 1, 1}	Z/z	52	{1, 1, 1, 3, 1, 1, 3}	\$
26	{3, 3, 3, 3, 3}	0	53	{1, 3, 3, 1, 3, 1}	@

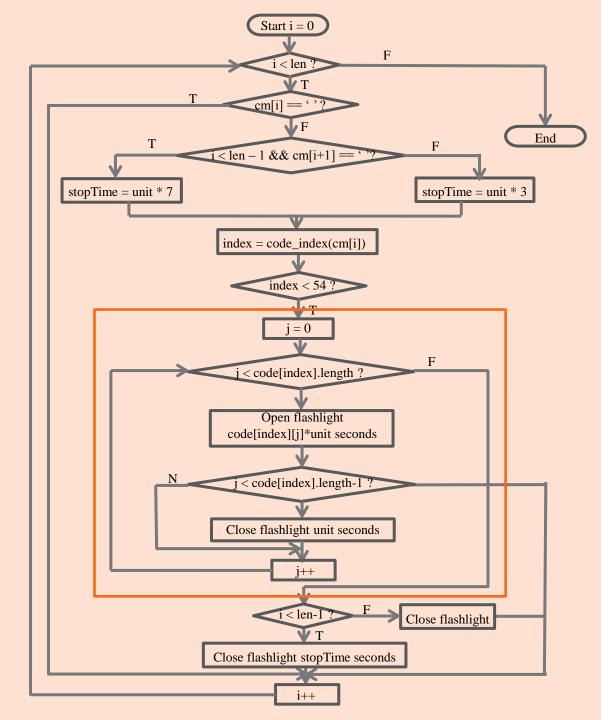
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Project demo



cm[]: the array of message inputted.len: length of cm[].

': space

index: the index of Morse code array. Code[][]: The Morse code array.

Example : "A E" Morse code: "-----" cm[] = {'A', ' ', 'E'} len = 3

Index = code_index(cm[i]) i = 0 index = 0, code[0][] = $\{1, 3\}$

i = 1 index = 54

i = 2 index = 4, code[2][] = {1}

DECODING

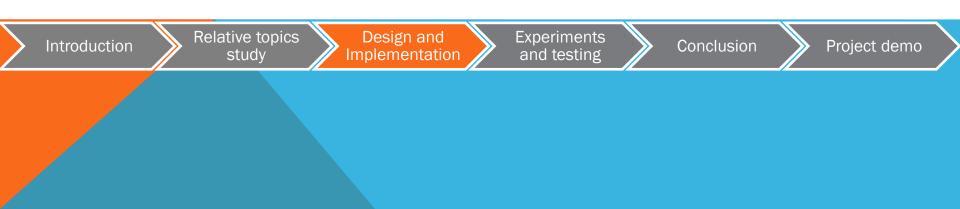
Open the camera

- Create the preview
- · Get each frame of the real time image
- Convert frame to RGBA32

Set parameters for camera

- Keep the screen on
- Enable the view

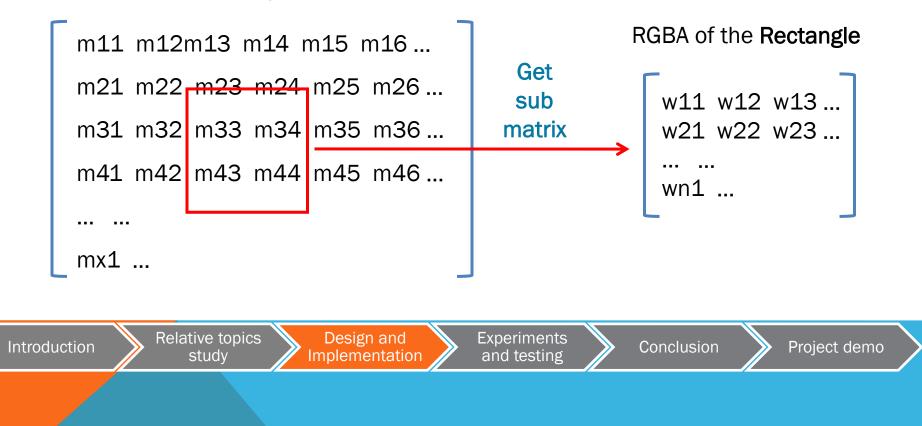
Process frame values



DECODING — process frame values

• Draw rectangle in the image

RGBA of the input frame



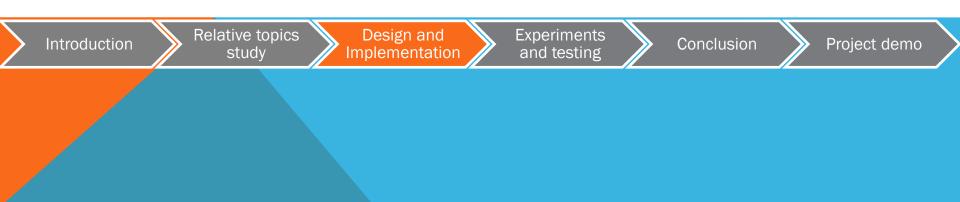
DECODING - process frame values

- Threshold value of each pixel's Light ON/OFF
 - Step1: Light fully fill the rectangle
 - Step2: Sum of all elements in the rectangle
 - Step3: Average value

Threshold value for each channel:

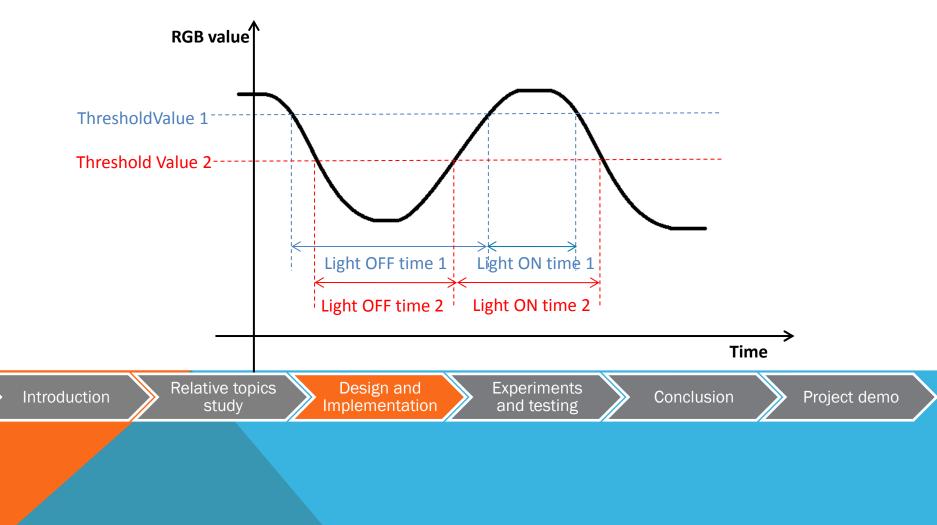
T(R) = 210 T(G) = 210 T(B) = 210

V(R) > 210 && V(G) > 210 && V(B) > 210 Pixel is Light ON



DECODING - process frame values

• Duration of Light ON/OFF



DECODING - process frame values

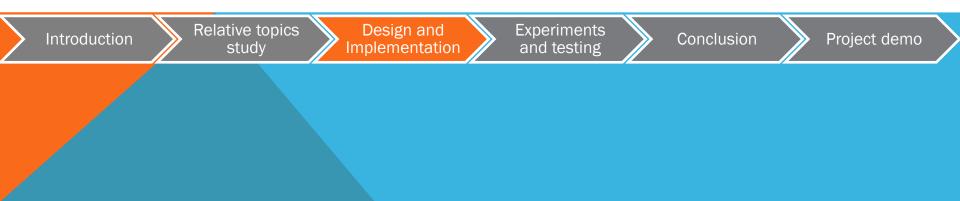
Duration of Light ON/OFF

newTime = $\begin{bmatrix} dot & 0.7 * dot < realTime < 1.3 * dot \\ 3 * dot & 2.5 * dot < realTime < 3.5 * dot \\ 7 * dot & 6.5 * dot < realTime < 7.5 * dot \end{bmatrix}$

• Decode

Make use of duration of Light ON/OFF

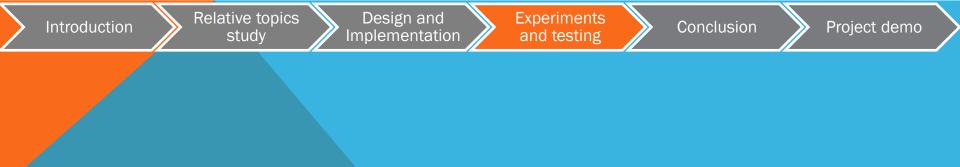
Match them to the Morse code pattern



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EXPERIMENTS AND TESTING - LIGHT ON/OFF

Actual Light OFF condition





EXPERIMENTS AND TESTING - LIGHT ON/OFF

Actual Light ON condition while...





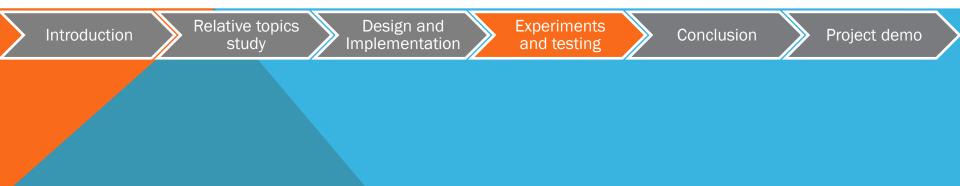
Light ON duration testing





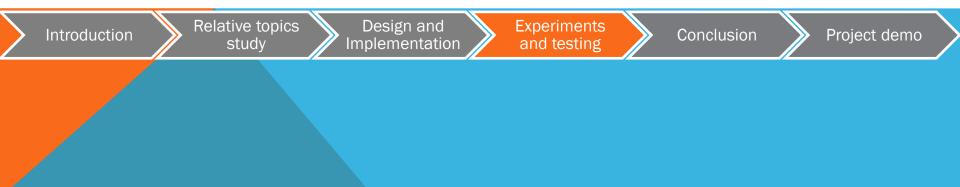
Symbol testing: 26 letters and numbers





Symbol testing: Punctuations

Last Light ON state: DOT Light off The code is: ;=+ ''\$@ ,?'!. /()&:		Lost Light ON state: DOT	
	SMIS	Light off	



Minimum emitting rate --- determined by dot duration

Dot duration < 0.5 s === > errors happened in decoding

Rule: emitting rate < receiving rate / 2

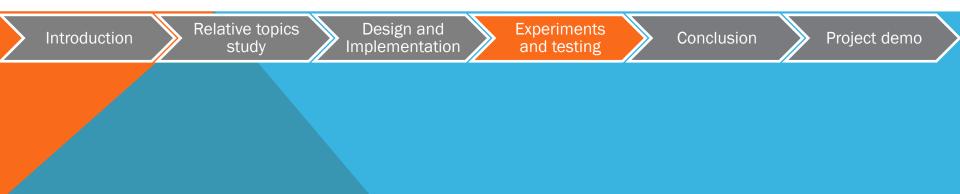
Suppose receiving frequency = FPS

Emitting rate = 1 / (Dot duration) Hz

The max(emitting rate) = FPS / 2.

Our camera FPS = 8 fps max(emitting rate) = 8 / 2 Hz

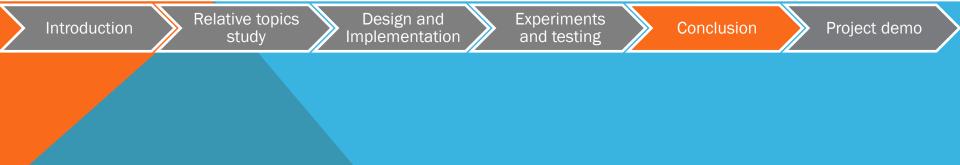
min(dot duration) = 2/8 s = 0.25s



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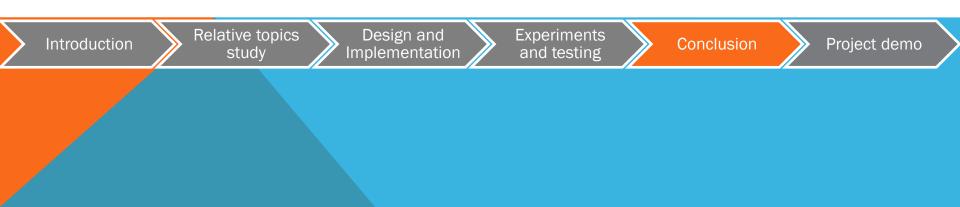
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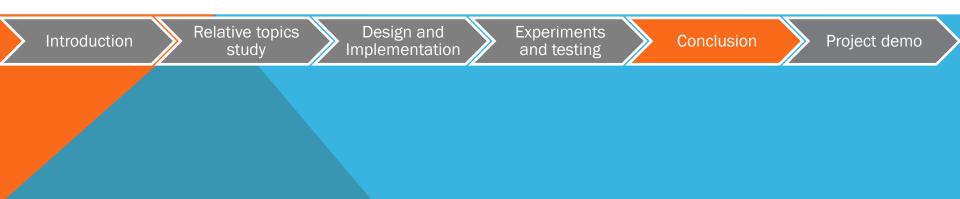
CURRENT LIMITATIONS

- Separated apps
- Unchangeable transmission rate
- Nonautomatic decoding
- Disturbance of environmental light
- Low accuracy under high transmission rate.
- Unchangeable parameters of the environmental light, e.g. exposure value



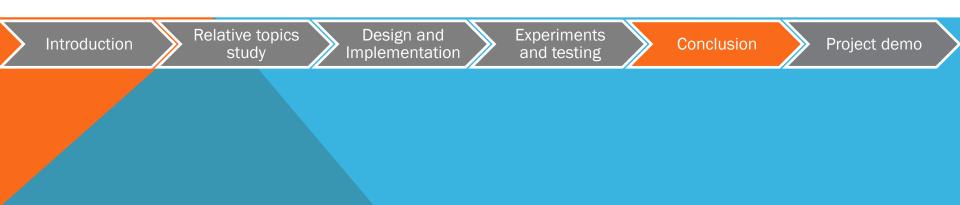
DIFFICULTIES

- For the whole project:
- Without any knowledge about Android programming and Java
- For the encoding part:
- Flashlight control
- Timing control
- For the decoding part:
- No idea about OpenCV
- RGBA values process
- ON/OFF duration process



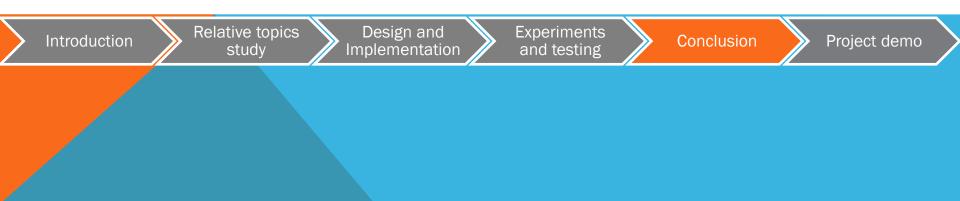
FUTURE DEVELOPMENT

- For the whole project:
- Combination of the two apps
- User Interface optimization
- Accuracy improvement
- Bi-directional communication in the standard way



FUTURE DEVELOPMENT

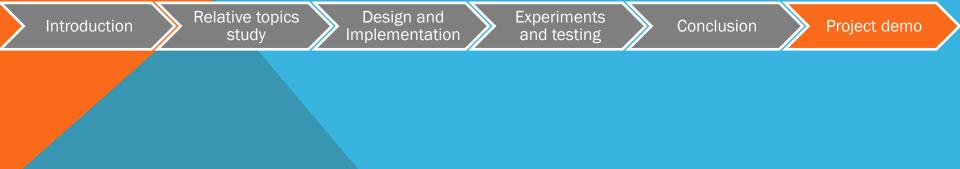
- For the encoding part:
- Changeable transmission rate
- For the decoding part:
- Longer distance decoding
- Higher transmission rate decoding
- Auto-detection
- Changeable parameters, e.g. brightness, exposure



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