

# Lecture Notes: An Output-Sensitive Algorithm for 2D Maxima

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In this lecture, we will revisit the *maxima problem* defined. Let us recall the relevant definitions. Given two different points  $(x_1, y_1)$  and  $(x_2, y_2)$  in  $\mathbb{R}^2$ , we say that the former *dominates* the latter if  $x_1 \geq x_2$  and  $y_1 \geq y_2$  (note that the two equalities cannot hold simultaneously because these are two different points). Let  $P$  be a set of  $n$  points in  $\mathbb{R}^2$ . A point  $p \in P$  is a *maximal point* of  $P$  if  $p$  is not dominated by any point in  $P$ . The goal is to report all the maximal points of  $P$  efficiently. In the example of Figure 1, points 1, 2, 6, and 8 should be reported.

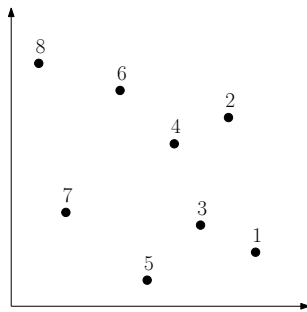


Figure 1: An example

The problem can be easily solved in  $O(n \log n)$  time. Today, we will give an *output-sensitive* algorithm that finishes in  $O(n \log k)$  time, where  $k$  is the number of maximal points. The technique behind this algorithm can be deployed to obtain output-sensitive algorithms for other problems as well, e.g., convex hull.

Before continuing, let us first observe a simple  $O(nk)$  time algorithm. First, find the rightmost point  $p$  of  $P$  in  $O(n)$  time, which must be a maximal point. Then, in  $O(n)$  time remove from  $P$  (i) all the points dominated by  $p$  and also (ii)  $p$  itself. Now, the rightmost point of (the remaining)  $P$  is also guaranteed to be a maximal point. Repeat the above steps until  $P$  becomes empty.

## 1 Utilizing An Upper Bound of $k$

Let us first assume that, by magic, we know an upper bound  $\hat{k}$  of  $k$  (e.g.,  $\hat{k} = n$  is a trivial upper bound). We will design an algorithm whose efficiency depends on  $\hat{k}$ .

First, divide  $P$  by x-coordinate into  $\hat{k}$  subsets  $P_1, \dots, P_{\hat{k}}$  such that

- every point in  $P_i$  has a larger x-coordinate than all the points in  $P_j$  for any  $1 \leq i < j \leq \hat{k}$ ;
- $|P_1| = |P_2| = \dots = |P_{\hat{k}}| = O(n/\hat{k})$ .

This can be done in  $O(n \log \hat{k})$  time using a standard rank selection algorithm (see appendix).

Next, we process the subsets  $P_i$  in ascending order of  $i$ . As an invariant, after  $P_i$  has been processed, we must have computed the maximal points of  $P_1 \cup \dots \cup P_i$  (observe that they must also be maximal points of  $P$ ). We achieve the purpose as follows. First, all the maximal points of  $P_1$  are found in  $O(t_1 \cdot |P_1|) = O(t_1 \cdot n/\hat{k})$  time, where  $t_1$  is the number of those points. In general, assuming that the invariant holds after  $P_i$ , we process  $P_{i+1}$  as follows. Let  $p^*$  be the highest of all the maximal points in  $P_1 \cup \dots \cup P_i$ . Scan  $P_{i+1}$  to remove all the points dominated by  $p^*$ . Then, find all the maximal points of the *remaining*  $P_{i+1}$  in  $O(t_{i+1} \cdot |P_{i+1}|) = O(t_{i+1} \cdot n/\hat{k})$  time, where  $t_{i+1}$  is the number of those points. Note that all these points must also be maximal points of  $P_1 \cup \dots \cup P_{i+1}$ . Overall, we spend  $O((n/\hat{k}) \sum_{i=1}^k t_i) = O((n/\hat{k}) \cdot k) = O(n)$  time.

We thus have proved:

**Lemma 1.** *If an upper bound  $\hat{k}$  of  $k$  is known, we can find all the maximal points in at most  $cn \log \hat{k}$  time for some constant  $c$ .*

## 2 The Final Algorithm

Lemma 1 is not immediately helpful: if we set  $\hat{k}$  to the trivial bound  $n$ , then the running time  $O(n \log \hat{k})$  is no better than  $O(n \log n)$ . Next, we will employ the lemma in a clever way to achieve the desired  $O(n \log k)$  bound.

The main idea is to ask the algorithm take a guess  $k'$  of  $k$ . Initially, the algorithm sets  $k'$  to 1 and, if  $k' < k$  (i.e.,  $k'$  fails to be an upper bound of  $k$ , we increase our guess  $k'$  and repeat. Crucially, we can *detect* whether  $k' < k$  in  $O(n \log k')$  time, thanks to Lemma 1. Specifically, we simply run the algorithm of Section 1 by setting  $\hat{k} = k'$ , and keep monitoring the algorithm's cost (this means counting the number of unit-time atomic operations in the RAM model). If  $k' \geq k$ , then by Lemma 1, the algorithm should terminate within  $cn \log k'$  time. Hence, as soon as the algorithm's cost reaches  $1 + cn \log k'$ , we can manually terminate the algorithm and declare that  $k' < k$ .

Motivated by this, we start with  $k' = 2^1$ . If  $k' < k$ , we increase  $k'$  to  $2^2$  and try again. In general, if  $k' = 2^{2^i}$  is still smaller than  $k$ , the next  $k'$  we try is  $\min\{2^{2^{i+1}}, n\}$ . Clearly, this algorithm will eventually find all the maximal points: it does so when  $k'$  is at least  $k$  for the first time.

Suppose that eventually the algorithm stops at  $k' = 2^{2^i}$  for some integer  $i \geq 0$ . The total running time is:

$$\begin{aligned} & O\left(n \log 2^{2^0} + n \log 2^{2^1} + n \log 2^{2^2} + n \log 2^{2^3} + \dots + n \log 2^{2^i}\right) \\ &= O\left(n (2^0 + 2^1 + 2^2 + \dots + 2^i)\right) \\ &= O(n \cdot 2^i) \end{aligned}$$

How large is  $2^i$ ? The definition of  $i$  implies  $2^{2^{i-1}} < k$ , namely,  $2^i < 2 \log_2 k$ . We thus have obtained an algorithm solving the maxima problem in  $O(n \cdot 2^i) = O(n \log k)$  time.

## Appendix: Multi-Rank Selection

Let  $S$  be a set of  $n$  real values. We say that a value  $v \in S$  has rank  $i$  if  $|\{u \in S \mid u \geq v\}| = i$  (i.e., the largest value in  $S$  has rank 1, the second largest rank 2, ...). Given any rank  $r \in [1, n]$ , the element with rank  $r$  can be selected in linear time  $O(n)$  using a textbook rank selection algorithm.

In the *multi-rank selection problem*, suppose we are given  $k$  ranks  $r_1, \dots, r_k$  in ascending order, and need to find the  $k$  corresponding elements. This is do-able in  $O(n \log k)$  time as follows. Without loss of generality, let us assume that  $k$  is a power of 2. We first pick the median of  $r_{k/2}$  of  $\{r_1, \dots, r_k\}$ , and find the element  $e$  with rank  $r_{k/2}$ . Then, divide  $S$  into  $S_1$  and  $S_2$  such that (i) the former includes all the elements of  $S$  at least  $e$ , and (ii) the latter includes the other elements of  $S$ . We now recurse on two instances of the multi-rank selection problem: the first one on  $S_1$  with ranks  $r_1, \dots, r_{k/2}$ , and the second one on  $S_2$  with ranks  $r_{1+k/2} - k/2, r_{2+k/2} - k/2, \dots, r_k - k/2$ .

Let us analyze the running time. Define  $f(n, k)$  as the time of the above algorithm when  $k$  ranks are to be computed from an input set of size  $n$ . If  $k = 1$ , we know  $f(n, k) = O(n)$ . For  $k > 1$ , we have:

$$f(n, k) = f(|S_1|, k/2) + f(n - |S_1|, k/2).$$

Solving the recurrence gives  $f(n, k) = O(n \log k)$ .