Grid Decomposition — Finding the Closest or Close Pairs

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We will learn the grid decomposition method which is a powerful technique for solving many difficult problems in fixed-dimensional spaces. In particular, we will look at two such problems: closest pair and close pairs. These problems appear very similar to each other, but differ significantly in their solutions.
Let $P$ be a set of points $\mathbb{R}^d$. The objective of the closest pair problem is to output a pair of distinct points $p, q \in P$ that have the smallest distance to each other, or formally:

$$\text{dist}(p, q) = \min_{p_1, p_2 \in P, p_1 \neq p_2} \text{dist}(p, q).$$

where $\text{dist}(., .)$ represents the Euclidean distance of two points.

Let $P$ be a set of points $\mathbb{R}^d$, and $r$ a real value. The objective of the close pairs problem is to output all pairs of distinct points $p, q \in P$ satisfying:

$$\text{dist}(p, q) \leq r.$$
The answer is \((p_6, p_8)\).
Example: Close Pairs

Assume $r = 4\sqrt{2}$.

The answer is $\{(p_1, p_4), (p_1, p_2), (p_2, p_3), (p_2, p_6), (p_2, p_4), \ldots \}$. 
Applications

- “Find the closest pair of airplanes at 12pm on 1 Jan 2017.”
- “Find the closest pair of earthquake locations in the last 5 years.”
- “Find the two customers whose profiles are most similar to each other.”
- ...

All the above applications have their counterparts with respect to the close-pairs problem, e.g., “find all pairs of airplanes that were within 10km at 12pm on 1 Jan 2017”.
Next, we will first deal with the closest pair problem, and then attend to the close pairs problem. Note that both problems can be easily solved in $O(n^2)$ time, where $n = |P|$. We, on the other hand, aim to solve the first problem in $O(n \log n)$ expected time, and the second in $O(n + k)$ expected time, where $k$ is the number of pairs reported.
Warm Up: Closest Pair in 1D

Think: How to solve the 1D closest pair problem in $O(n \log n)$ time?

Hint: Sorting suffices.
Let us now turn our attention to 2D space. Naturally, we divide $P$ evenly using a vertical line $\ell$, such that there are $n/2$ points on each side. Let $P_1$ (or $P_2$) be the set of points on the left (or right) of $\ell$. We recursively find the closest pair in $P_1$, and then in $P_2$, respectively.

In the above example, the closest pair of $P_1$ is $(p_2, p_3)$, and that of $P_2$ is $(p_7, p_8)$. 
We need to “merge” the two halves to find the global closest pair. It suffices to find the closest pair \((p_1, p_2)\) satisfying \(p_1 \in P_1\) and \(p_2 \in P_2\)—namely, \(p_1, p_2\) come from different sides. Call it the crossing closest pair.

In the above example, the crossing closest pair is \((p_6, p_8)\). The global closest pair must be among the two “local” pairs \((p_2, p_3)\), \((p_7, p_8)\), and the crossing pair \((p_6, p_8)\).
We now explain how to find the crossing closest pair. Let $r_1$ be the distance of the closest pair in $P_1$, and $r_2$ be the distance of the closest pair in $P_2$. Define $r = \min\{r_1, r_2\}$.

In the above example, $r_1 = \sqrt{8}$, $r_2 = 3$, and $r = \min\{r_1, r_2\} = \sqrt{8}$.

**Observation:** We care about the crossing closest pair only if its distance is smaller than or equal to $r$. 
Closest Pair in 2D

Impose an arbitrary grid $G$ onto the data space, where (i) each cell is an axis-parallel square with side length $r/\sqrt{2}$, and (ii) $\ell$ is a line in the grid.

Each point $p$ can be covered by at most 4 cells (e.g., $p_9$ is covered by 4 cells, but $p_8$ by only 1 cell).
Closest Pair in 2D

For each cell $c$, we denote by $c(P)$ the set of points in $P$ that are covered by $c$.

**Observation:** For every $c$, $|c(P)| \leq 2 = O(1)$!

**Proof:** Note that the diagonal of $c$ has length $r$. If $c$ covers more than 2 points, at least 2 points have distance less than $r$—contradicting the definition of $r$!
Closest Pair in 2D

Group the points by the cells they belong. A cell is non-empty if it covers at least one point. There can be at most $4n$ non-empty cells.

In the above example, there are 25 non-empty cells.
Closest Pair in 2D

Each cell can be uniquely identified by the coordinates of its centroid—which we refer to as the id of the cell. Using hashing, by spending $O(n)$ expected time in total, we can create for each cell $c$, a linked list containing all the points in $c(P)$ (i.e., the set of points covered by $c$).
Let $c_1, c_2$ be two non-empty cells. We say that $c_1$ is an \textit{r-neighbor} of $c_2$ (and vice versa) if their mindist is at most $r$.

To find a crossing closest pair within distance $r$, it suffices to consider (the points in) non-empty cells $c_1, c_2$ satisfying (i) $c_1$ is on the left of $\ell$, and $c_2$ is on the right, and (ii) $c_1$ and $c_2$ are $r$-neighbors.

For example, Cell 11 is an $r$-neighbor of Cell 5, while Cell 15 is not. In other words, we need to consider the cell pair $(5, 11)$, but not $(5, 15)$.

Cells 1, 2, 3, 18, 19, 20, 21, 22, 23, 24, and 25 can be immediately discarded (why?).
Observation: Each non-empty cell $c$ on the left of $\ell$ has at most $10 = O(1)$ $r$-neighbor cells on the right of $\ell$.

For example, for Cell 8, we need to consider 8 pairs: (8, 10), (8, 11), (8, 12), (8, 13), (8, 14), (8, 15), (8, 16), (8, 17).
Closest Pair in 2D

The above discussion motivates the following algorithm for finding a crossing closest pair within distance $r$:

1. **for** every non-empty cell $c_1$ on the left of $\ell$
2. **for** every $r$-neighbor cell $c_2$ of $r_1$ on the right of $\ell$
3. calculate the distance of each pair of points $(p_1, p_2) \in c_1(P) \times c_2(P)$
4. **return** the closest one among all the pairs inspected at Line 3, if the pair has distance at most $r$.

As mentioned, for each $c_1$, there are $O(1)$ cells $c_2$ that need to be considered. Since $c_1(P)$ and $c_2(P)$ each contain at most 2 points, each execution of Line 3 takes only $O(1)$ time. The overall algorithm takes $O(n)$ expected time in total.

**Think:** How to find the cells $c_2$ for each $c_1$ in $O(1)$ expected time? **Hint:** by hashing on the cell ids.
Closest Pair in 2D: Analysis

Let $f(n)$ be the expected running time of our algorithm, it follows that

$$f(n) \leq 2 \cdot f(n/2) + O(n)$$

while $f(n) = O(1)$ for $n \leq 2$.

The recurrence solves to $f(n) = O(n \log n)$. 
Closest Pair in $d$-dimensional Space

Our algorithm can be extended directly to $d$-dimensional space.

The only difference is that, we should impose a $d$-dimensional grid, where each cell is a $d$-dimensional square with side length $r/\sqrt{d}$ (this ensures that a diagonal of every cell has length $r$).

Recall that, to ensure $O(n \log n)$ running time, we relied on the following fact in 2D:

Each non-empty cell $c_1$ on the left of $\ell$ has $O(1)$ $r$-neighbor cells $c_2$ on the right of $\ell$.

We will prove that this is true regardless of $d$ (as long as $d$ is a constant, i.e., it has nothing related to $n$).

Plugging this fact into the earlier analysis immediately shows that the algorithm runs in $O(n \log n)$ expected time for any constant $d$. 
**Closest Pair in $d$-dimensional Space**

**Lemma:** In $d$-dimensional space, each non-empty cell $c_1$ on the left of $\ell$ has $O(1)$ non-empty cells $c_2$ on the right of $\ell$ satisfying $\text{mindist}(c_1, c_2) \leq r$.

**Proof:** Extend each boundary face of $c_1$ outwards by a length of $r$. This gives a $d$-dimensional square of side length $2r + r/\sqrt{d}$. The square intersects with at most

\[
\left[ 2 + \frac{2r + r/\sqrt{d}}{r/\sqrt{d}} \right]^d \leq \left[ 2\sqrt{d} + 3 \right]^d = O(1).
\]

Remark: The calculation in the proof is very loose. For example, many of the cells in the “enlarged” square are on the left of $\ell$, but are counted anyway. However, the number of cells is still $O(1)$ even after the over-counting.
The success behind our grid decomposition technique in the closest-pair problem comes from the property that, each cell in the grid has $O(1)$ $r$-neighbor cells.

We now proceed to tackle the close-pairs problem by essentially using the same property. Recall that our objective is to achieve $O(n + k)$ expected time, where $k$ is the number of pairs reported.
Recall the definition of the close-pairs problem.

Let $P$ be a set of distinct points $\mathbb{R}^d$, and $r$ a real value. The objective of the close pairs problem is to output all pairs of distinct points $p, q \in P$ satisfying:

$$\text{dist}(p, q) \leq r.$$ 

We will focus on 2D space, because the algorithm can be directly extended to arbitrary dimensionalities.
We will explain the algorithm using the same dataset and $r = 4\sqrt{2}$.

**Step 1:** Impose an arbitrary grid where each square cell has side length $r/\sqrt{2} = 4$. Identify all the non-empty cells (there are 8 such cells in our example).
Close Pairs in 2D

Step 2: For each cell $c$, let $c(P)$ be the set of points covered by $c$. Simply report all pairs of distinct points in $c(P)$—notice that any two points in the same cell must have distance at most $r$.

For example, 1 pair is reported for Cell 1, and 3 pairs for Cell 8.
**Step 3:** For each cell $c_1$, identify all of its $r$-neighbor cells $c_2$. For every $c_2$, inspect all pairs of distinct points $(p_1, p_2) \in c_1(P) \times c_2(P)$, and report the ones within distance at most $r$.

For example, from Cells 2, 4, inspect all the 8 pairs in \( \{p_2, p_3\} \times \{p_4, p_6, p_7, p_8\} \), and report \((p_2, p_4), (p_2, p_6), (p_3, p_6)\).
Close Pairs in 2D: Analysis

Next, we will prove that our algorithm runs in $O(n + k)$ expected time. At first glance, this may look a bit surprising. Recall that in Step 3, for each pair of $r$-neighbor cells $(c_1, c_2)$, we spend a quadratic amount of time $O(|c_1(P)||c_2(P)|)$, but risk finding no answer pairs at all. Indeed, the core of the analysis is to show that the total time of doing so is bounded by $O(n + k)$.

We will focus on Steps 2 and 3 because Step 1 obviously takes $O(n)$ expected time (by hashing).
Close Pairs in 2D: Analysis (Step 2)

Let $c_1, c_2, ..., c_m$ be the non-empty cells, for some $m \geq 1$. Define $n_i = |c_i(P)|$, namely, the number of points covered by $c_i$, for each $i \in [1, m]$. Clearly $\sum_{i=1}^{m} n_i \geq n$.

The cost of Step 2 is obviously

$$\sum_{i=1}^{m} O(n_i^2)$$

Notice that

$$k \geq \sum_{i=1}^{m} n_i(n_i - 1)/2 = \frac{1}{2} \sum_{i=1}^{m} n_i^2 - \frac{1}{2} \sum_{i=1}^{m} n_i \geq \frac{1}{2} \left( \sum_{i=1}^{m} n_i^2 \right) - \frac{n}{2}.$$ 

We thus have

$$\sum_{i=1}^{m} O(n_i^2) = O(n + k).$$
We will prove that the cost of Step 3 is $\sum_{i=1}^{m} O(n_i^2)$, and therefore, bounded by $O(n + k)$.

Let $c_i$ and $c_j$ be a pair of $r$-neighbor cells. Step 3 spends $O(n_i \cdot n_j)$ time to process $c_i(P) \times c_j(P)$. Clearly:

$$n_i \cdot n_j \leq \frac{n_i^2 + n_j^2}{2}.$$
Close Pairs in 2D: Analysis (Step 3)

The total cost of Step 3 can be written as

$$O \left( \sum_{i=1}^{m} \sum_{j: c_j \text{ is an } r\text{-neighbor of } c_i} n_i \cdot n_j \right)$$

= $$O \left( \sum_{i=1}^{m} \sum_{j: c_j \text{ is an } r\text{-neighbor of } c_i} (n_i^2 + n_j^2) \right)$$

(by the inequality of the previous slide)

As a cell has $O(1)$ $r$-neighbor cells, we know that each $n_i^2$ can appear only $O(1)$ times in the above summation. Therefore, the summation is bounded by $O(\sum_{i=1}^{m} n_i^2)$.

We now conclude that the running time of our close-pairs algorithm is $O(n + k)$ expected.