# Greedy 1: Activity Selection

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In this lecture, we will commence our discussion of **greedy** algorithms, which enforce a simple strategy: make the **locally optimal** decision at each step. Although this strategy does not always guarantee finding a **globally optimal** solution, sometimes it does. The nontrivial part is to prove (or disprove) the global optimality.

**Input:** A set S of n intervals of the form [s, f] where s and f are integers. **Output:** A subset T of disjoint intervals in S with the largest size |T|.

**Remark:** You can think of [s, f] as the duration of an activity, and consider the problem as picking the largest number of activities that do not have time conflicts.

#### **Example:** Suppose

$$S = \{[1, 9], [3, 7], [6, 20], [12, 19], [15, 17], [18, 22], [21, 24]\}.$$

 $T = \{[3, 7], [15, 17], [18, 22]\}$  is an optimal solution, and so is  $T = \{[1, 9], [12, 19], [21, 24]\}$ .

#### **Algorithm**

Repeat until *S* becomes empty:

- Add to T the interval  $\mathcal{I} \in S$  with the smallest finish time.
- Remove from S all the intervals intersecting  $\mathcal{I}$  (including  $\mathcal{I}$  itself)

**Example:** Suppose  $S = \{[1, 9], [3, 7], [6, 20], [12, 19], [15, 17], [18, 22], [21, 24]\}.$ 

Let us rearrange the intervals in S in ascending order of finish time:  $S = \{[3,7], [1,9], [15,17], [12,19], [6,20], [18,22], [21,24]\}.$ 

We first add [3,7] to T, after which intervals [3,7], [1,9] and [6,20] are removed. Now S becomes  $\{[15,17],[12,19],[18,22],[21,24]\}$ . The next interval added to T is [15,17], which shrinks S further to  $\{[18,22],[21,24]\}$ . After [18,22] is added to T, S becomes empty and the algorithm terminates.

Next, we will prove that the algorithm returns an optimal solution. Let us start with a crucial claim.

Claim 1: Let  $\mathcal{I}_1$  be the first interval picked by our algorithm. There must be an optimal solution containing  $\mathcal{I}_1$ .

**Proof:** Let  $T^*$  be an arbitrary optimal solution. If  $\mathcal{I}_1 \in T^*$ , Claim 1 is true and we are done. Next, we assume  $\mathcal{I}_1 \notin T^*$ .

We will turn  $T^*$  into another optimal solution T containing  $\mathcal{I}$ . For this purpose, first identify the interval  $\mathcal{I}_1'$  in  $T^*$  with the **smallest** finish time. Construct T as follows: add all the intervals in  $T^*$  to T except  $\mathcal{I}'$ , and finally add  $\mathcal{I}$  to T.

We will prove that all the intervals in T are disjoint. This indicates that T is also an optimal solution, and hence, will complete the proof.

It suffices to prove that  $\mathcal{I}_1$  cannot intersect with any other interval in  $\mathcal{J} \in \mathcal{T}$ . This is true because

- the start time of  $\mathcal{J}$  is after the finish time of  $\mathcal{I}_1'$ ;
- the finish time of  $\mathcal{I}_1$  is less than or equal to the finish time of  $\mathcal{I}'_1$ .

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Claim 2: Let  $\mathcal{I}_1, \mathcal{I}_2, ..., \mathcal{I}_k$  be the first  $k \geq 2$  intervals picked by our algorithm (in the order shown). Assume that there is an optimal solution containing  $\mathcal{I}_1, ..., \mathcal{I}_{k-1}$ . Then, there must exist an optimal solution containing  $\mathcal{I}_1, ..., \mathcal{I}_{k-1}, \mathcal{I}_k$ .

**Proof:** Let  $T^*$  be an optimal solution containing  $\mathcal{I}_1, ..., \mathcal{I}_{k-1}$ . Observe:

All the intervals in  $T^* \setminus \{\mathcal{I}_1, ..., \mathcal{I}_{k-1}\}$  must start strictly after the finish time of  $\mathcal{I}_{k-1}$ .

Think: Why?

If  $\mathcal{I}_k \in \mathcal{T}^*$ , Claim 2 is true and we are done. Next, we consider the case where  $\mathcal{I}_k \notin \mathcal{T}^*$ .

Let  $\mathcal{I}'_k$  be the interval in  $T^* \setminus \{\mathcal{I}_1,...,\mathcal{I}_{k-1}\}$  that has the smallest finish time. Construct a set T of intervals as follows: add all the intervals of  $T^*$  to T except  $\mathcal{I}'_k$ , and finally add  $\mathcal{I}_k$  to T.

To prove that T is an optimal solution, it suffices to prove that  $\mathcal{I}_k$  is disjoint with every interval  $\mathcal{J} \in T^* \setminus \{\mathcal{I}_1,...,\mathcal{I}_{k-1},\mathcal{I}'_k\}$ . This is true because

- the start time of  $\mathcal{J}$  is after the finish time of  $\mathcal{I}'_k$ ;
- the finish time of  $\mathcal{I}_k$  is less than or equal to the finish time of  $\mathcal{I}'_k$ .

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**Think:** How to implement the algorithm in  $O(n \log n)$  time?

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