# Dynamic Programming 5: Optimal BST

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- Each node stores a key.
- The key of an internal node *u* is larger than any key in the left subtree of u, and smaller than any key in the right subtree of u.

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- The **level** of a node u in a BST T denoted as  $level_T(u)$  equals the number of edges on the path from the root to u.
  - The level of the root is 0.
- The depth of a tree is the maximum level of the nodes in the tree.
- Searching for a node u incurs cost proportional to  $1 + level_T(u)$ .

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Let *S* be a set of *n* integers. We have learned (from CSCI2100) that a balanced BST on *S* has depth  $O(\log n)$ . This is good if all the integers in *S* are searched with equal probabilities.

In practice, not all keys are equally important: some are searched **more often than others**. This gives rise to an interesting question:

If we know the search frequencies of the integers in S, how to build a better BST to minimize the average search cost?



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The Optimal BST Problem

Input:

- A set *S* of *n* integers: {1, 2, ..., *n*};
- An array W where W[i]  $(1 \le i \le n)$  stores a positive integer weight.

**Output:** A BST *T* on *S* with the smallest average cost

$$avgcost(T) = \sum_{i=1}^{n} W[i] \cdot cost_{T}(i).$$

where  $cost_T(i) = 1 + level_T(i)$  is the number of nodes accessed to find the key *i* in *T*.

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We will solve a more general version of the problem.

#### Input:

- S and W same as before;
- Integers a, b satisfying  $1 \le a \le b \le n$ .

**Output:** A BST T on  $\{a, a + 1, ..., b\}$  with the smallest **average cost**:

$$avgcost(T) = \sum_{i=a}^{b} W[i] \cdot cost_T(i).$$

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**Fact:** The root of *T* must have a key  $r \in [a, b]$ .

After the root key *r* is fixed, we know:

- the root's left subtree is a BST  $T_1$  on  $S_1 = \{a, ..., r-1\}$ , and
- the root's right subtree is a BST  $T_2$  on  $S_2 = \{r + 1, ..., b\}$ .



**Lemma:** Let T,  $T_1$ , and  $T_2$  be defined as above. Then:

$$avgcost(T) = \left(\sum_{i=a}^{b} W[i]\right) + avgcost(T_1) + avgcost(T_2).$$

### **Proof:**

$$\begin{aligned} & \operatorname{avgcost}(T) \\ &= \sum_{i=a}^{b} W[i] \cdot \operatorname{cost}_{T}(i) = \sum_{i=a}^{b} W[i] \cdot (1 + \operatorname{level}_{T}(i)) \\ &= \left(\sum_{i=a}^{b} W[i]\right) + \sum_{i=a}^{b} W[i] \cdot \operatorname{level}_{T}(i) \\ &= \left(\sum_{i=a}^{b} W[i]\right) + \left(\sum_{i=a}^{r-1} W[i] \cdot \operatorname{level}_{T}(i)\right) + \left(\sum_{i=r+1}^{b} W[i] \cdot \operatorname{level}_{T}(i)\right) \end{aligned}$$

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$$= \left(\sum_{i=a}^{b} W[i]\right) + \left(\sum_{i=a}^{r-1} W[i] \cdot (1 + level_{T_1}(i))\right) + \left(\sum_{i=r+1}^{b} W[i] \cdot (1 + level_{T_2}(i))\right)$$
$$= \left(\sum_{i=a}^{b} W[i]\right) + \left(\sum_{i=a}^{r-1} W[i] \cdot cost_{T_1}(i)\right) + \left(\sum_{i=r+1}^{b} W[i] \cdot cost_{T_2}(i)\right)$$
$$= \left(\sum_{i=a}^{b} W[i]\right) + avgcost(T_1) + avgcost(T_2).$$



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Define optavg(a, b) as

• 0, if *a* > *b*;

• the smallest average cost of a BST on  $\{a, a+1, ..., b\}$ , otherwise.

Define optavg(a, b | r) as the optimal average cost of a BST, on condition that the BST has  $r \in [a, b]$  as the key of the root.

By the previous lemma, we have:

$$optavg(a, b | r)$$
  
=  $\left(\sum_{i=a}^{b} W[i]\right) + optavg(a, r-1) + optavg(r+1, b).$ 

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**Example:**  $S = \{1, 2, 3, 4\}; W = (40, 15, 35, 10).$ 

Consider choosing 2 as the root key.

$$optavg(1, 4 | 2)$$
  
=  $\left(\sum_{i=1}^{4} W[i]\right) + optavg(1, 1) + optavg(3, 4)$   
=  $100 + 40 + 55 = 195.$ 

Hence, **among all BSTs with root key 2**, the best BST has average cost 195.

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The recursive structure of the problem:

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$$optavg(a, b) = \min_{r=a}^{b} optavg(a, b \mid r) \\ = \left(\sum_{i=a}^{b} W[i]\right) + \min_{r=a}^{b} \left\{ optavg(a, r-1) + optavg(r+1, b) \right\}.$$

With dynamic programming, we can compute optavg(1, n) in  $O(n^3)$  time (left as a special exercise).

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Strictly speaking, we have not produced the optimal BST yet. However, fixing the issue should be fairly standard to you at this moment: the piggyback technique allows you to build the tree in the same time complexity as computing opt(1, n). This is left as a special exercise.