## CSCI3160: Regular Exercise Set 9

Prepared by Yufei Tao

Problem 1*. Prove the correctness of Dijkstra's algorithm (when the edges have non-negative weights).

Solution. We argue that, every time a vertex $v$ is removed from $S$ (note: each time the algorithm removes from a vertex $v$ from $S$ with the smallest dist $(v)$; see the algorithm's description in the lecture slides), we must have $\operatorname{dist}(v)=\operatorname{spdist}(v)$. We will do so by induction on the order that the vertices are removed. The base step, which corresponds to removing the source vertex $s$, is obviously correct. Next, assuming correctness on all the vertices already removed, we will prove the statement on the vertex $v$ removed next.

Let $\pi$ be an arbitrary shortest path from $s$ to $v$. Identify the first vertex $u$ on $\pi$ (in the direction from $s$ to $v$ ) such that $\operatorname{spdist}(u)=\operatorname{spdist}(v)$. In other words, all the edges on $\pi$ between $u$ and $v$ have weight 0 . Let $\pi^{\prime}$ be the prefix of $\pi$ that ends at $u$. Note that $\pi^{\prime}$ must be a shortest path from $s$ to $u$.


Claim 1: When $v$ is to be removed from $S$, all the vertices on $\pi^{\prime}$ - except possibly $u$ must have been removed from $S$.

Proof of Claim 1: Suppose that the claim is not true. Define $v_{b a d}$ as the first vertex on $\pi^{\prime}$ that is still in $S$ when $v$ is to be removed from $S$. Let $v_{g o o d}$ be the vertex right before $v_{\text {bad }}$ on $\pi$; note that $v_{\text {good }}$ definitely exists because $v_{b a d}$ cannot be $s$. By how $u$ is defined, we must have $\operatorname{spdist}\left(v_{b a d}\right)<\operatorname{spdist}(u)=\operatorname{spdist}(v)$.


By our inductive assumption, when $v_{\text {good }}$ was removed from $S$, we had $\operatorname{dist}\left(v_{\text {good }}\right)=\operatorname{spdist}\left(v_{\text {good }}\right)$. We must have relaxed the edge ( $v_{\text {good }}, v_{b a d}$ ), after which we must have

$$
\begin{aligned}
\operatorname{dist}\left(v_{\text {bad }}\right) & =\operatorname{dist}\left(v_{\text {good }}\right)+w\left(v_{\text {good }}, v_{\text {bad }}\right) \\
& =\operatorname{spdist}\left(v_{\text {good }}\right)+w\left(v_{\text {good }}, v_{\text {bad }}\right)=\operatorname{spdist}\left(v_{\text {bad }}\right) .
\end{aligned}
$$

The value $\operatorname{dist}\left(v_{b a d}\right)$ never increases during the algorithm. Hence, when $v$ is to be removed from $S$, we must have $\operatorname{dist}\left(v_{b a d}\right)=\operatorname{spdist}\left(v_{b a d}\right)<\operatorname{spdist}(u)=\operatorname{spdist}(v) \leq \operatorname{dist}(v)$. But this contradicts the fact that $v$ has the smallest dist-value among all the vertices still in $S$.

Consider the moment when $v$ is to be removed from $S$; define $z$ as the first vertex on $\pi$ that has not been removed from $S$. Note that $z$ is well defined because $v$ itself is still in $S$ at this moment.


Claim 2: When $v$ is to be removed from $S$, $\operatorname{dist}(z)=\operatorname{spdist}(z)$.

Proof of Claim 2: Let $z^{\prime}$ be the vertex right before $z$ on $\pi$. Note that $z^{\prime}$ is well defined because $z$ cannot be earlier than $u$ on $\pi$ (Claim 1) and $z$ cannot be $s$.

By our inductive assumption, when $z^{\prime}$ was removed from $S$, we had $\operatorname{dist}\left(z^{\prime}\right)=\operatorname{spdist}\left(z^{\prime}\right)$. We must have relaxed the edge $\left(z^{\prime}, z\right)$, after which we must have

$$
\operatorname{dist}(z)=\operatorname{dist}\left(z^{\prime}\right)+w\left(z^{\prime}, z\right)=\operatorname{spdist}\left(z^{\prime}\right)=\operatorname{spdist}(z) .
$$

It now follows that, when $v$ is to be removed from $S$, we have $\operatorname{dist}(v) \leq \operatorname{dist}(z)=\operatorname{spdist}(z)=$ $\operatorname{spdist}(v)$. As $\operatorname{dist}(v)$ cannot be larger than $\operatorname{spdist}(v)$, we must have $\operatorname{dist}(v)=\operatorname{spdist}(v)$.

Problem 2. Consider again your proof for Problem 1. Point out the place that requires edge weights to be non-negative.

Solution. We used this assumption in the proof of Claim 1: look for the sentence: "By how $u$ is defined, we must have $\operatorname{spdist}\left(v_{b a d}\right)<\operatorname{spdist}(u)=\operatorname{spdist}(v)$ ".

Problem 3. Consider a directed simple graph $G=(V, E)$ where each edge $e \in E$ has an arbitrary weight $w(e)$ (which can be negative). It is known that $G$ does not have negative cycles. Prove: given any vertices $s, t \in V$, at least one shortest path from $s$ to $t$ is a simple path (i.e., no vertex appears twice on the path).

Remark: This implies that the path must have at most $|V|-1$ edges.
Solution. Let $\pi$ be a shortest path from $s$ to $t$ that uses the least number of edges. We will prove that $\pi$ must be a simple path. Let us list all the vertices on the path from $s$ to $t$ as $u_{1}, u_{2}, \ldots, u_{t}$, where $u_{1}=s, u_{t}=t$, and $t-1$ is the number of edges on $\pi$. If $\pi$ is not a simple path, then there must exist $1 \leq i<j \leq t$ with $u_{i}=u_{j}$. Thus, the sub-path $u_{i}, u_{i+1}, \ldots, u_{j-1}, u_{j}$ is a cycle. The length of the cycle must be non-negative. By removing this sub-path, we obtain another path $\pi^{\prime}$ from $s$ to $t: u_{1}, u_{2}, \ldots, u_{i}, u_{j+1}, u_{j+2}, \ldots, t$. The new path $\pi^{\prime}$ cannot have a length greater than $\pi$, but uses strictly fewer edges. This contradicts the definition of $\pi$.

Problem 4* (SSSP in a DAG). Consider a simple acyclic directed graph $G=(V, E)$ where each edge $e \in E$ has an arbitrary weight $w(e)$ (which can be negative). Solve the SSSP problem on $G$ in $O(|V|+|E|)$ time.

Solution. Let $s$ be the source vertex. For each vertex $v \in V$, define $\operatorname{spdist}(v)$ as the shortest path length from $s$ to $v$. Also, define $\operatorname{IN}(v)$ as the set of in-neighbors of $v$. Observe that:

$$
\operatorname{spdist}(v)= \begin{cases}0 & \text { if } v=s \\ \infty & \text { if } \operatorname{IN}(v)=\emptyset \\ \min _{u \in \operatorname{IN}(v)}(\operatorname{spdist}(u)+w(u, v)) & \text { if } v \neq s \text { and } \operatorname{IN}(v) \neq \emptyset\end{cases}
$$

We can compute $\operatorname{spdist}(v)$ in $O(|V|+|E|)$ time based on a topological order of $V$, which can also be obtained in $O(|V|+|E|)$ time (see Prof. Tao's CSCI2100 homepage). The shortest path tree of $s$ can then be obtained using the piggyback technique without increasing the time complexity.

Problem 5. Let $G=(V, E)$ be a simple directed graph where each edge $e \in E$ carries a weight $w(e)$, which can be negative. It is guaranteed that $G$ has no negative cycles. Prove: given any vertices $s, t \in V$, at least one shortest path from $s$ to $t$ is a simple path (i.e., no vertex appears twice on the path).

Solution. Consider a shortest path $\pi$ from $s$ to $t$ that has the least number of edges. We argue that $\pi$ must be simple. Otherwise, at least one vertex $v$ appears twice on $\pi$. Identify any two consecutive occurrences of $v$ - call the first occurrence $v_{1}$ and the second $v_{2}$. Thus, the subpath of $\pi$ from $v_{1}$ to $v_{2}$ is a cycle. As $G$ does not have any negative cycle, that subpath must have a non-negative length. We can now remove the subpath from $\pi$ to obtain another shortest path from $s$ to $t$ that has fewer edges than $\pi$.

Problem 6**. Let $G=(V, E)$ be a simple directed graph where the weight of an edge $(u, v)$ is $w(u, v)$. Prove: the following algorithm correctly decides whether $G$ has a negative cycle.

## algorithm negative-cycle-detection

pick an arbitrary vertex $s \in V$
initialize $\operatorname{dist}(s)=0$ and $\operatorname{dist}(v)=\infty$ for every other vertex $v \in V$
for $i=1$ to $|V|-1$
relax all the edges in $E$
for each edge $(u, v) \in E$
if $\operatorname{dist}(v)>\operatorname{dist}(u)+w(u, v)$ then
7. return "there is a negative cycle"
8. return "no negative cycles"

Solution. We will prove two directions.
Direction 1: If the inequality of Line 6 holds for any edge $(u, v)$, then there must be a negative cycle. The lecture proved that, in the absence of negative cycles, Bellman-Ford's algorithm correctly finds all shortest path distances (from $s$ ) after $|V|-1$ rounds of edge relaxations. This means that, if there are no cycles, when we come to Line 6 , the value $\operatorname{dist}(v)$ must be the shortest path distance from $s$ to $v$, for every $v \in V$. If Line 6 holds for some edge $(u, v)$, however, it means that an even shorter path from $s$ to $v$ has just been discovered. Therefore, $G$ must contain a negative cycle.

Direction 2: If there is a negative cycle, then the inequality of Line 6 must hold for at least one edge $(u, v)$. Suppose that the negative cycle is $v_{1} \rightarrow v_{2} \rightarrow \ldots \rightarrow v_{\ell} \rightarrow v_{1}$. Hence:

$$
\begin{equation*}
w\left(v_{\ell}, v_{1}\right)+\sum_{i=1}^{\ell-1} w\left(v_{i}, v_{i+1}\right)<0 \tag{1}
\end{equation*}
$$

Assume that Line 6 does not hold on any edge in $E$. This indicates:

- for every $i \in[1, \ell-1], \operatorname{dist}\left(v_{i+1}\right) \leq \operatorname{dist}\left(v_{i}\right)+w\left(v_{i}, v_{i+1}\right)$;
- $\operatorname{dist}\left(v_{1}\right) \leq \operatorname{dist}\left(v_{\ell}\right)+w\left(v_{\ell}, v_{1}\right)$.

These two bullets lead to:

$$
\begin{aligned}
\sum_{i=1}^{\ell} \operatorname{dist}\left(v_{i}\right) & \leq\left(\sum_{i=1}^{\ell} \operatorname{dist}\left(v_{i}\right)\right)+w\left(v_{\ell}, v_{1}\right)+\sum_{i=1}^{\ell-1} w\left(v_{i}, v_{i+1}\right) \\
\Rightarrow 0 & \leq w\left(v_{\ell}, v_{1}\right)+\sum_{i=1}^{\ell-1} w\left(v_{i}, v_{i+1}\right)
\end{aligned}
$$

which contradicts (1).

