## Exercises: Eigenvalues and Eigenvectors

Problem 1. Find all the eigenvalues and eigenvectors of $\boldsymbol{A}=\left[\begin{array}{lll}0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0\end{array}\right]$.
Solution. Let $\lambda$ be an eigenvalue of $\boldsymbol{A}$. To obtain all possible $\lambda$, we solve the characteristic equation of $\boldsymbol{A}$ (let $\boldsymbol{I}$ be the $3 \times 3$ identity matrix):

$$
\begin{aligned}
\operatorname{det}(\boldsymbol{A}-\lambda \boldsymbol{I}) & =0 \Rightarrow \\
\left|\begin{array}{ccc}
-\lambda & 0 & 1 \\
0 & 1-\lambda & 0 \\
1 & 0 & -\lambda
\end{array}\right| & =0 \Rightarrow \\
(\lambda-1)^{2}(\lambda+1) & =0
\end{aligned}
$$

Hence, $\boldsymbol{A}$ has eigenvalues $\lambda_{1}=1$ and $\lambda_{2}=-1$.
To find all the eigenvectors of $\lambda_{1}=1$, we need to solve $\boldsymbol{x}=\left[\begin{array}{l}x_{1} \\ x_{2} \\ x_{3}\end{array}\right]$ from:

$$
\begin{aligned}
\left(\boldsymbol{A}-\lambda_{1} \boldsymbol{I}\right) \boldsymbol{x} & =\mathbf{0} \Rightarrow \\
{\left[\begin{array}{ccc}
-1 & 0 & 1 \\
0 & 0 & 0 \\
1 & 0 & -1
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3}
\end{array}\right] } & =\left[\begin{array}{l}
0 \\
0 \\
0
\end{array}\right]
\end{aligned}
$$

The set of solutions to the above equation-EigenSpace $\left(\lambda_{1}\right)$-includes all $\left[\begin{array}{l}x_{1} \\ x_{2} \\ x_{3}\end{array}\right]$ satisfying

$$
\begin{aligned}
x_{1} & =u \\
x_{2} & =v \\
x_{3} & =u
\end{aligned}
$$

for any $u, v \in \mathbb{R}$. Any non-zero vector in $\operatorname{EigenSpace}\left(\lambda_{1}\right)$ is an eigenvector of $\boldsymbol{A}$ corresponding to $\lambda_{1}$.

Similarly, to find all the eigenvectors of $\lambda_{2}=-1$, we need to solve $\boldsymbol{x}=\left[\begin{array}{l}x_{1} \\ x_{2} \\ x_{3}\end{array}\right]$ from:

$$
\begin{aligned}
\left(\boldsymbol{A}-\lambda_{2} \boldsymbol{I}\right) \boldsymbol{x} & =\mathbf{0} \Rightarrow \\
{\left[\begin{array}{lll}
1 & 0 & 1 \\
0 & 2 & 0 \\
1 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
x_{1} \\
x_{2} \\
x_{3}
\end{array}\right] } & =\left[\begin{array}{l}
0 \\
0 \\
0
\end{array}\right]
\end{aligned}
$$

The set of solutions to the above equation-EigenSpace $\left(\lambda_{2}\right)$-includes all $\left[\begin{array}{c}x_{1} \\ x_{2} \\ x_{3}\end{array}\right]$ satisfying

$$
\begin{aligned}
& x_{1}=u \\
& x_{2}=0 \\
& x_{3}=-u
\end{aligned}
$$

for any $u \in \mathbb{R}$. Any non-zero vector in EigenSpace $\left(\lambda_{2}\right)$ is an eigenvector of $\boldsymbol{A}$ corresponding to $\lambda_{2}$.
Problem 2. Let $\boldsymbol{A}$ be an $n \times n$ square matrix. Prove: $\boldsymbol{A}$ and $\boldsymbol{A}^{T}$ have exactly the same eigenvalues.
Proof. Recall that an eigenvalue of a matrix is a root of the matrix's characteristic equation, which equates the matrix's characteristic polynomial to 0 . It suffices to show that the characteristic polynomial of $\boldsymbol{A}$ is the same as that of $\boldsymbol{A}^{T}$. In other words, we want to show that $\operatorname{det}(\boldsymbol{A}-\lambda \boldsymbol{I})=$ $\operatorname{det}\left(\boldsymbol{A}^{T}-\lambda \boldsymbol{I}\right)$. This is true because $\boldsymbol{A}-\lambda \boldsymbol{I}=\left(\boldsymbol{A}^{T}-\lambda \boldsymbol{I}\right)^{T}$.

Problem 3 (Hard). Let $\boldsymbol{A}$ be an $n \times n$ square matrix. Prove: $\boldsymbol{A}^{-1}$ exists if and only if 0 is not an eigenvalue of $\boldsymbol{A}$.

Proof. If-Direction. The objective is to show that if 0 is not an eigenvalue of $\boldsymbol{A}$, then $\boldsymbol{A}^{-1}$ exists, namely, the rank of $\boldsymbol{A}$ is $n$. Suppose, on the contrary, that the rank of $\boldsymbol{A}$ is less than $n$. Consider the linear system $\boldsymbol{A} \boldsymbol{x}=\mathbf{0}$ where $\boldsymbol{x}$ is an $n \times 1$ matrix. The hypothesis that rank $\boldsymbol{A}<n$ indicates that the system has infinitely many solutions. In other words, there exists a non-zero $\boldsymbol{x}$ satisfying $\boldsymbol{A} \boldsymbol{x}=\mathbf{0} \boldsymbol{x}=\mathbf{0}$. This, however, indicates that 0 is an eigenvalue of $\boldsymbol{A}$, which is a contradiction.

Only-If Direction. The objective is to show that if $\boldsymbol{A}^{-1}$ exists, then 0 is not an eigenvalue of $\boldsymbol{A}$. The existence of $\boldsymbol{A}^{-1}$ means that the rank of $\boldsymbol{A}$ is $n$, which in turn indicates that $\boldsymbol{A} \boldsymbol{x}=\mathbf{0}$ has a unique solution $\boldsymbol{x}=\mathbf{0}$. In other words, there is no non-zero $\boldsymbol{x}^{\prime}$ satisfying $\boldsymbol{A} \boldsymbol{x}^{\prime}=\mathbf{0} \boldsymbol{x}^{\prime}$, namely, 0 is not an eigenvalue of $\boldsymbol{A}$.

Problem 4. Let $\boldsymbol{A}$ be an $n \times n$ square matrix such that $\boldsymbol{A}^{-1}$ exists. Prove: if $\lambda$ is an eigenvalue of $\boldsymbol{A}$, then $1 / \lambda$ is an eigenvalue of $\boldsymbol{A}^{-1}$.

Proof. Since $\lambda$ is an eigenvalue of $\boldsymbol{A}$, there is a non-zero $n \times 1$ matrix $\boldsymbol{x}$ satisfying

$$
\begin{aligned}
\boldsymbol{A} \boldsymbol{x} & =\lambda \boldsymbol{x} \Rightarrow \\
\boldsymbol{A}^{-1} \boldsymbol{A} \boldsymbol{x} & =\lambda \boldsymbol{A}^{-1} \boldsymbol{x} \Rightarrow \\
\boldsymbol{x} & =\lambda \boldsymbol{A}^{-1} \boldsymbol{x} \Rightarrow \\
\boldsymbol{A}^{-1} \boldsymbol{x} & =(1 / \lambda) \boldsymbol{x}
\end{aligned}
$$

which completes the proof.
Problem 5. Prove: if $\boldsymbol{A}^{2}=\boldsymbol{I}$, then the eigenvalues of $\boldsymbol{A}$ must be 1 or -1 .
Proof. Consider any eigenvalue $\lambda$ of $\boldsymbol{A}$, and let $\boldsymbol{x}$ be an arbitrary eigenvector of $\boldsymbol{A}$ corresponding to $\lambda$. Hence, we have:

$$
\begin{aligned}
\boldsymbol{A} \boldsymbol{x} & =\lambda \boldsymbol{x} \Rightarrow \\
\boldsymbol{A}^{2} \boldsymbol{x} & =\lambda \boldsymbol{A x} \Rightarrow \\
\boldsymbol{I} \boldsymbol{x} & =\lambda \boldsymbol{A x} \Rightarrow \\
\boldsymbol{x} & =\lambda \boldsymbol{A} \boldsymbol{x}
\end{aligned}
$$

Note that $\lambda(\boldsymbol{A} \boldsymbol{x})=\lambda(\lambda \boldsymbol{x})=\lambda^{2} \boldsymbol{x}$. Hence, we have

$$
\boldsymbol{x}=\lambda^{2} \boldsymbol{x}
$$

As $\boldsymbol{x}$ is not $\mathbf{0}$, it follows that $\lambda^{2}=1$, which completes the proof.

Problem 6. Suppose that $\lambda_{1}$ and $\lambda_{2}$ are two distinct eigenvalues of matrix $\boldsymbol{A}$. Furthermore, suppose that $\boldsymbol{x}_{1}$ is an eigenvector of $\boldsymbol{A}$ under $\lambda_{1}$, and that $\boldsymbol{x}_{2}$ is an eigenvector of $\boldsymbol{A}$ under $\lambda_{2}$. Prove: there does not exist any real number $c$ such that $c \boldsymbol{x}_{1}=\boldsymbol{x}_{2}$.

Proof. Assume, on the contrary, that such a $c$ exists. Since $\boldsymbol{A} \boldsymbol{x}_{1}=\lambda_{1} \boldsymbol{x}_{1}$, we have $\boldsymbol{A}\left(c \boldsymbol{x}_{1}\right)=$ $\lambda_{1}\left(c \boldsymbol{x}_{1}\right)$, which leads to $\boldsymbol{A} \boldsymbol{x}_{2}=\lambda_{1} \boldsymbol{x}_{2}$.

On the other hand, $\boldsymbol{A} \boldsymbol{x}_{2}=\lambda_{2} \boldsymbol{x}_{2}$. Therefore, $\lambda_{1}=\lambda_{2}$ (remember $\boldsymbol{x}_{2}$ cannot be $\mathbf{0}$ ), giving a contradiction.

Problem 7. Suppose that $\lambda_{1}$ and $\lambda_{2}$ are two distinct eigenvalues of matrix $\boldsymbol{A}$. Furthermore, suppose that $\boldsymbol{x}_{1}$ is an eigenvector of $\boldsymbol{A}$ under $\lambda_{1}$, and that $\boldsymbol{x}_{2}$ is an eigenvector of $\boldsymbol{A}$ under $\lambda_{2}$. Prove: $\boldsymbol{x}_{1}+\boldsymbol{x}_{2}$ is not an eigenvector of $\boldsymbol{A}$.

Proof. Assume, on the contrary, that $\boldsymbol{x}_{1}+\boldsymbol{x}_{2}$ is an eigenvector under some eigenvalue $\lambda_{3}$. This means that

$$
\begin{aligned}
\boldsymbol{A}\left(\boldsymbol{x}_{1}+\boldsymbol{x}_{2}\right) & =\lambda_{3}\left(\boldsymbol{x}_{1}+\boldsymbol{x}_{2}\right) \Rightarrow \\
\boldsymbol{A} \boldsymbol{x}_{1}+\boldsymbol{A} \boldsymbol{x}_{2} & =\lambda_{3}\left(\boldsymbol{x}_{1}+\boldsymbol{x}_{2}\right) \Rightarrow \\
\lambda_{1} \boldsymbol{x}_{1}+\lambda_{2} \boldsymbol{x}_{2} & =\lambda_{3}\left(\boldsymbol{x}_{1}+\boldsymbol{x}_{2}\right) \Rightarrow \\
\left(\lambda_{1}-\lambda_{3}\right) \boldsymbol{x}_{\mathbf{1}} & =\left(\lambda_{3}-\lambda_{2}\right) \boldsymbol{x}_{\mathbf{2}} .
\end{aligned}
$$

As $\lambda_{1} \neq \lambda_{2}$, at least one of $\lambda_{1}-\lambda_{3}$ and $\lambda_{3}-\lambda_{2}$ is non-zero. Without loss of generality, suppose $\lambda_{3}-\lambda_{2} \neq 0$, which gives:

$$
\frac{\lambda_{1}-\lambda_{3}}{\lambda_{3}-\lambda_{2}} \boldsymbol{x}_{\mathbf{1}}=\boldsymbol{x}_{\mathbf{2}}
$$

In Problem 6, we already showed that the above is impossible, thus giving a contradiction.

