

CENG3420

Lecture 10: Virtual Memory & Performance

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Overview

Introduction

 $\begin{array}{c} \text{Virtual Memory} \\ \text{VA} \rightarrow \text{PA} \\ \text{TLB} \end{array}$

Performance Issues





Overview

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Virtual Memory $VA \rightarrow PA$ TLB

Performance Issues





Motivations

Physical memory may not be as large as "possible address space" spanned by a processor, e.g.

- A processor can address 4G bytes with 32-bit address
- But installed main memory may only be 1GB

How if we want to simultaneously run many programs which require a total memory consumption greater than the installed main memory capacity?

Terminology:

- A running program is called a process or a thread
- Operating System (OS) controls the processes





Virtual Memory

- ▶ Use main memory as a "cache" for secondary memory
- ► Each program is compiled into its own virtual address space
- ► What makes it work? Principle of Locality





Virtual Memory

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Why virtual memory?

- During run-time, virtual address is translated to a physical address
- Efficient & safe sharing memory among multiple programs
- Ability to run programs larger than the size of physical memory
- Code relocation: code can be loaded anywhere in main memory





Bottom of the Memory Hierarchy

Consider the following example:

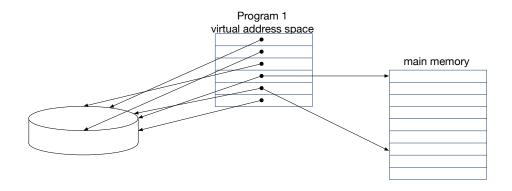
- Suppose we hit the limit of 1GB in the example, and we suddenly need some more memory on the fly.
- We move some main memory chunks to the harddisk, say, 100MB.
- ▶ So, we have 100MB of "free" main memory for use.
- What if later on, those instructions / data in the saved 100MB chunk are needed again?
- We have to "free" some other main memory chunks in order to move the instructions / data back from the harddisk.





Two Programs Sharing Physical Memory

► A program's address space is divided into pages (fixed size) or segments (variable sizes)

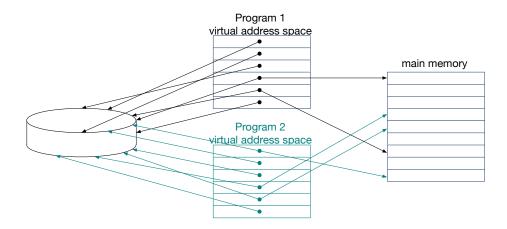






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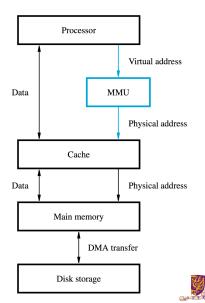






Virtual Memory Organization

- Part of process(es) are stored temporarily on harddisk and brought into main memory as needed
- This is done automatically by the OS, application program does not need to be aware of the existence of virtual memory (VM)
- Memory management unit (MMU) translates virtual addresses to physical addresses





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Address Translation

- Memory divided into pages of size ranging from 2KB to 16KB
 - Page too small: too much time spent getting pages from disk
 - Page too large: a large portion of the page may not be used
 - This is similar to cache block size issue (discussed earlier)
- ► For harddisk, it takes a considerable amount of time to locate a data on the disk but once located, the data can be transferred at a rate of several MB per second.
- ▶ If pages are too large, it is possible that a substantial portion of a page is not used but it will occupy valuable space in the main memory.





Address Translation

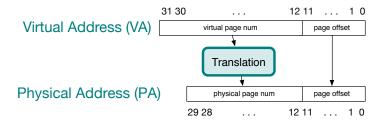
- ► An area in the main memory that can hold one page is called a page frame.
- Processor generates virtual addresses
 - MS (high order) bits are the virtual page number
 - LS (low order) bits are the offset
- Information about where each page is stored is maintained in a data structure in the main memory called the page table
 - Starting address of the page table is stored in a page table base register
 - Address in physical memory is obtained by indexing the virtual page number from the page table base register





Address Translation

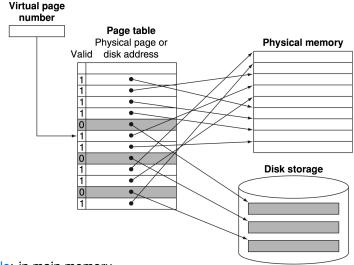
- ▶ Virtual address → physical address by combination of HW/SW
- Each memory request needs first an address translation
- Page Fault: a virtual memory miss

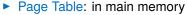






Address Translation Mechanisms





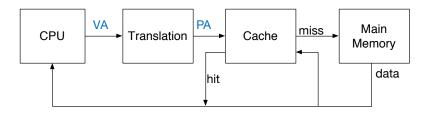
Process: page table + program counter + registers



Virtual Addressing with a Cache

Disadvantage of virtual addressing:

- One extra memory access to translate a VA to a PA
- memory (cache) access very expensive...

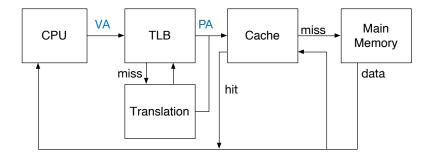






Translation Look-aside Buffer (TLB)

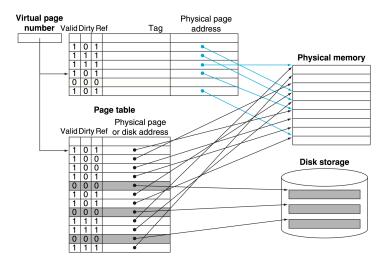
- ► A small cache: keeps track of recently used address mappings
- Avoid page table lookup







Translation Look-aside Buffer (TLB)



- Dirty bit:
- ► Ref bit:





More about TLB

Organization:

Just like any other cache, can be fully associative, set associative, or direct mapped.

Access time:

- Faster than cache: due to smaller size
- Typically not more than 512 entries even on high end machines

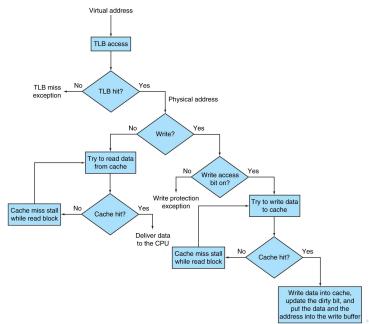
A TLB miss:

- If the page is in main memory: miss can be handled; load translation info from page table to TLB
- If the page is NOT in main memory: page fault





Cooperation of TLB & Cache





TLB Event Combinations

- ► TLB / Cache miss: page / block not in "cache"
- Page Table miss: page NOT in memory

TLB	Page Table	Cache	Possible? Under what circumstances?
Hit	Hit	Hit	
Hit	Hit	Miss	
Miss	Hit	Hit	
Miss	Hit	Miss	
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Miss	Miss	Miss	
Hit	Miss	Miss / Hit	
Miss	Miss	Hit	





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Hit	Hit	Hit	Yes – what we want!
Hit	Hit	Miss	Yes – although page table is not
			checked if TLB hits
Miss	Hit	Hit	Yes – TLB miss, PA in page table
Miss	Hit	Miss	Yes – TLB miss, PA in page table but
			data not in cache
Miss	Miss	Miss	Yes – page fault
Hit	Miss	Miss / Hit	
Miss	Miss	Hit	





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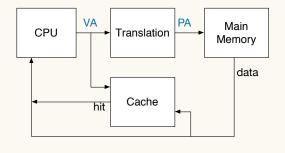
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			data not in cache
Miss	Miss	Miss	Yes – page fault
Hit	Miss	Miss / Hit	Impossible – TLB translation not possible
			if page is not in memory
Miss	Miss	Hit	Impossible – data not allowd in cache if
			page is not in memory





QUESTION: Why Not a Virtually Addressed Cache?

- Access Cache using virtual address (VA)
- ▶ Only address translation when cache misses



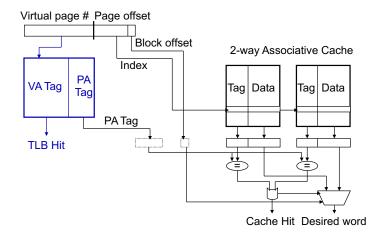
Answer:





Overlap Cache & TLB Accesses

- ► High order bits of VA are used to access TLB
- Low order bits of VA are used as index into cache







The Hardware / Software Boundary

Which part of address translation is done by hardware?

- ► TLB that caches recent translations.
 - TLB access time is part of cache hit time
 - May allot extra stage in pipeline
- Page Table storage, fault detection and updating
 - Dirty & Reference bits
 - Page faults result in interrupts
- Disk Placement:





The Hardware / Software Boundary

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 - Page faults result in interrupts (Software)
- Disk Placement: (Software)





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Q1: Where A Block Be Placed in Upper Level?

Scheme name	# of sets	Blocks per set
Direct mapped	# of blocks	1
Set associative	# of blocks Associativity	Associativity
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Q2: How Is Entry Be Found?

Scheme name	Location method	# of comparisons
Direct mapped	Index	1
Set associative	Index the set; compare set's tags	Degree of associativity
Fully associative	Compare all tags	# of blocks





Q3: Which Entry Should Be Replaced on a Miss?

- Direct mapped: only one choice
- Set associative or fully associative:
 - Random
 - LRU (Least Recently Used)

Note that:

- For a 2-way set associative, random replacement has a miss rate 1.1× than LRU
- For high level associativity (4-way), LRU is too costly





Q4: What Happen On A Write?

- ► Write-Through:
 - ▶ The information is written in both the block in cache & the block in lower level of memory
 - Combined with write buffer, so write waits can be eliminated
 - **▶** ⊕:
 - **▶** ⊕:

▶ Write-Back.

- The information is written only to the block in cache
- ▶ The modification is written to lower level, only when the block is replaced
- Need dirty bit: tracks whether the block is clean or not
- Virtual memory always use write-back
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- The modification is written to lower level, only when the block is replaced
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- Virtual memory always use write-back
- : write with speed of cache
- ► ⊕: repeated writes require only one write to lower level





Performance Consideration

Performance

How **fast** machine instructions can be brought into the processor and how **fast** they can be executed.

- ► Two key factors are performance and cost, i.e., price/performance ratio.
- ► For a hierarchical memory system with cache, the processor is able to access instructions and data more quickly when the data wanted are in the cache.
- ► Therefore, the impact of a cache on performance is dependent on the hit and miss rates.





Cache Hit Rate and Miss Penalty

- ► High hit rates over 0.9 are essential for high-performance computers.
- A penalty is incurred because extra time is needed to bring a block of data from a slower unit to a faster one in the hierarchy.
- During that time, the processor is stalled.
- The waiting time depends on the details of the cache operation.

Miss Penalty

Total access time seen by the processor when a miss occurs.





Miss Penalty

Example: Consider a computer with the following parameters:

Access times to the cache and the main memory are t and 10t respectively. When a cache miss occurs, a block of 8 words will be transferred from the MM to the cache. It takes 10t to transfer the first word of the block and the remaining 7 words are transferred at a rate of one word per t seconds.

- ► Miss penalty = $t + 10t + 7 \times t + t$
- First t: Initial cache access that results in a miss.
- Last t: Move data from the cache to the processor.





Average Memory Access Time

$$h \times C + (1 - h) \times M$$

- ▶ *h*: hit rate
- ▶ M: miss penalty
- ► C: cache access time
- ▶ High cache hit rates (> 90%) are essential
- Miss penalty must also be reduced





Question: Memory Access Time Example

- Assume 8 cycles to read a single memory word;
- 15 cycles to load a 8-word block from main memory (previous example);
- cache access time = 1 cycle
- ► For every **100** instructions, statistically **30** instructions are data read/ write
- ▶ Instruction fetch: 100 memory access: assume hit rate = 0.95
- ▶ Data read/ write: 30 memory access: assume hit rate = 0.90

Calculate: (1) Execution cycles without cache; (2) Execution cycles with cache.





Caches on Processor Chips

- ▶ In high-performance processors, two levels of caches are normally used, L1 and L2.
- L1 must be very fast as they determine the memory access time seen by the processor.
- ▶ L2 cache can be slower, but it should be much larger than the L1 cache to ensure a high hit rate. Its speed is less critical because it only affects the miss penalty of the L1 cache.
- Average access time on such a system:

$$h_1 \cdot C_1 + (1 - h_1) \cdot [h_2 \cdot C_2 + (1 - h_2) \cdot M]$$

- \blacktriangleright h_1 (h_2): the L1 (L2) hit rate
- $ightharpoonup C_1$ the access time of L1 cache,
- C₂ the miss penalty to transfer data from L2 cache to L1
- ▶ *M*: the miss penalty to transfer data from MM to L2 and then to L1.





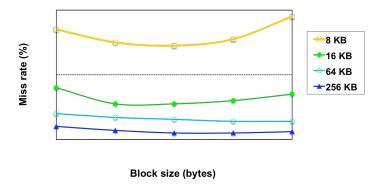
Larger Block Size

- Take advantage of spatial locality.
- ⑤ If all items in a larger block are needed in a computation, it is better to load these items into the cache in a single miss.
- Second Example 2 Larger blocks are effective only up to a certain size, beyond which too many items will remain unused before the block is replaced.
- Substituting the second of the second of
- Block sizes of 16 to 128 bytes are most popular.





Miss Rate v.s. Block Size v.s. Cache Size



Miss rate goes up if the block size becomes a significant fraction of the cache size because the number of blocks that can be held in the same size cache is smaller (increasing capacity misses)



Enhancement

Write buffer:

- Read request is served first.
- Write request stored in write buffer first and sent to memory whenever there is no read request.
- The addresses of a read request should be compared with the addresses of the write buffer.

Prefetch:

- Prefetch data into the cache before they are needed, while the processor is busy executing instructions that do not result in a read miss.
- Prefetch instructions can be inserted by the programmer or the compiler.

Load-through Approach

Instead of waiting the whole block to be transferred, the processor resumes execution as soon as the required word is loaded in the cache.

