# Community Detection Using Time-Dependent Personalized PageRank

#### Haim Avron Joint work with Lior Horesh

IBM T. J. Watson Research Center

32nd International Conference on Machine Learning (ICML 2015) July 7, 2015

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- Input: an *n* node undirected, unweighted graph.
- Community detection: find a set of nodes that are both internally cohesive and well separated
- We consider *community detection using seed node*:
  - Given a seed node, find a community around it

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## Community Detection Using Local Diffusions

A popular framework:

- Compute a diffusion vector
- 2 Reweight the vector based on degrees
- **③** Sort the nodes in decreasing order
- **3** Select a prefix that maximizes (or minimizes) some scoring function, e.g. conductance  $\phi(S) \equiv \frac{\partial S}{\min(\text{vol}(S), \text{vol}(\overline{S}))}$

Can be rigorously analyzed (Andersen et al., 2006; Chung, 2009)...

... but in practice multiple diffusions/parameters/scores are used to generate "interesting points" in the combinatorial search space.

#### PageRank and Heat Kernel Diffusion Vectors

#### • Notation:

- $\mathbf{A} \in \mathbb{R}^{n \times n}$  is the adjacency matrix
- $\mathbf{D} \in \mathbb{R}^{n imes n}$  is diagonal matrix of degrees
- $\mathbf{P} \equiv \mathbf{A}\mathbf{D}^{-1}$  (random walk transition matrix)
- $\mathbf{s} \in \mathbb{R}^n$  with 1 at seed, 0 elsewhere
- Personalized PageRank:

$$\mathbf{p} \equiv (1 - \alpha)(\mathbf{I}_n - \alpha \mathbf{P})^{-1}\mathbf{s}$$

• Heat Kernel:

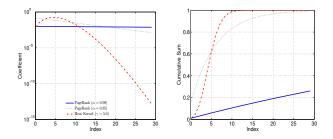
$$\mathbf{h} \equiv \exp\left\{-\gamma (\mathbf{I}_n - \mathbf{P})\right\} \mathbf{s}$$

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Diffusion vectors can be written as a series:

$$\mathbf{f} = \sum_{k=0}^{\infty} \alpha_k \mathbf{P}^k \mathbf{s}$$

$$\alpha_k^{pr} = (1 - \alpha)\alpha^k \qquad \alpha_k^{hk} = e^{-\gamma} \frac{\gamma^k}{k!}$$



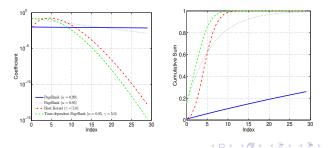
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#### Time-Dependent PageRank

$$\mathbf{x} \equiv (1-\alpha)(\mathbf{I}_n - \alpha \mathbf{P})^{-1} \mathbf{s} + \exp\{-\gamma(\mathbf{I}_n - \alpha \mathbf{P})\} (\mathbf{s} - (1-\alpha)(\mathbf{I}_n - \alpha \mathbf{P})^{-1} \mathbf{s})$$

$$\alpha_k^{tpr} = \left[ \left( 1 - \sum_{r=0}^k \alpha_r^{hk} \right) \alpha_k^{pr} + \alpha^k \alpha_k^{hk} \right]$$

Generalized both:  $\alpha = 1$  is heat kernel,  $\gamma \rightarrow \infty$  is PageRank



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### The Importance of Being Local

- Even if the graph is huge, communities tend to be local
  - Running time should be proportional to community size
- Diffusion vectors are typically dense
  - $\Omega(n)$  to compute them exactly
- However most values are tiny
- $\bullet$  Literature: A reasonably approximation  $f^\star$  to f is one that

$$\|\mathbf{D}^{-1}(\mathbf{f}^{\star}-\mathbf{f})\|_{\infty} < \epsilon$$

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 There are sparse vectors that uphold this (when ε is not too small)

# Local Algorithms for Local Diffusions

- Coordinate relaxation approach:
  - Write diffusion vector as solution to a linear system
  - Use a semi-greedy coordinate relaxation iteration (related to Gauss-Southwell rule)
  - General method for sparse approx of linear system solution
- Algorithms based on this approach:
  - Andersen et al. (2006) PageRank ("push" alg.)
  - Kloster & Gleich (2014) Heat Kernel (hkgrow)
- Our contribution: a local algorithm for Time-Dependent Personalized PageRank
- Main challenge: it does not translate to linear system
  - Do coordinate relaxation on a system of ODEs instead
  - Local approximation to system of ODE solution

### Underlying Observations

x = x(γ) where x(·) is the solution to
 x'(t) = (1 - α)s - (I<sub>n</sub> - αP)x(t) x(0) = s
 Let y(·) be an approx solution. The *residual* of y(·) is

$$\mathbf{r}(t) \equiv (1-lpha)\mathbf{s} - (\mathbf{I}_n - lpha \mathbf{P})\mathbf{y}(t) - \mathbf{y}'(t)$$

**Proposition:**  $\mathbf{y}(\cdot)$  is good enough if for all *i* 

$$\|r_i(\cdot)\|_{\infty} < \frac{(1-\alpha)d_i\epsilon}{1-\exp((\alpha-1)\gamma)}$$

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Suggests a coordinate relaxation type algorithm:

1 Initialize  $\mathbf{y}(t) = s$ .

2 While there exists a violating i

- Select such an *i* arbitrarily.
- **2** Set  $y_i(\cdot)$  to the solution of the ODE

$$y'(t) = -y(t) + \alpha \sum_{j=1}^{n} \mathbf{P}_{ij} y_j(t) + (1-\alpha) s_i \quad y(0) = s_i$$

However, this "algorithm" requires operations on infinite dimensional objects, and so is not viable.

#### From Infinite to Finite Dimension

- Use degree N polynomials
- $N = O(\gamma + \log(1 + \epsilon))$  (see paper for details)
- Polynomials are represented as samples on N + 1 scaled and shifted Chebyshev points

$$\mathbb{S}_{N}[p(\cdot)] \equiv \left[ \begin{array}{ccc} p(p_{0}) & \cdots & p(t_{N}) \end{array} 
ight]^{T} t_{j} = (\cos(j\pi/N) + 1)\gamma/2$$

- Need to map operations of the "algorithm":
  - Computing derivative (for residual computation)
  - Computing infinity norm of iterates (testing convergence)
  - Solving the ODE

# Computing Residual (aka Computing Derivative)

- The residual is a degree N polynomial as well (derivative of a polynomial is a reduced degree polynomial)
- Derivative is a linear operation, so exists  $\Xi \in \mathbb{R}^{(N+1) \times (N+1)}$  s.t.

$$\mathbb{S}_N[p'(\cdot)] = \Xi \mathbb{S}_N[p(\cdot)]$$

 $\bullet\,$  Formulas for  $\Xi$  is easily derived from well known formulas

$$\Xi_{ij} = \begin{cases} \gamma(1+2N^2)/12 & i=j=0\\ -\gamma(1+2N^2)/12 & i=j=N\\ \gamma x_j/(4-4x_j^2) & i=j; \ 0 < j < N\\ (-1)^{i+j}p_i/(2p_jx_i-p_jx_j) & i \neq j \end{cases}$$

where  $x_i = \cos(\pi i/N)$ ,  $p_0 = p_N = 2$ , and  $p_j = 1$  otherwise.

# Testing Convergence

- Amounts to bounding the infinity norm of polynomials
- Can be computed exactly, but expensive  $(O(N^3))$
- Proposition:

$$\|p(\cdot)\|_{\infty} \leq (1+\frac{2}{\pi}\log N)\|\mathbb{S}_N[p(\cdot)]\|_{\infty}$$
.

• Convergence test: for all *i* 

$$\|\mathbf{r}_i\|_{\infty} < \frac{(1-lpha)d_i\epsilon}{(1-\exp((lpha-1)\gamma))(1+rac{2}{\pi}\log N)}$$

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# Solving the ODE

- $\bullet\,$  The solution of the ODE is normally not a polynomial
  - So ODE can only be solved approximately
- Write the update as:

$$\mathbb{S}_N[y_i(\cdot)] \leftarrow \mathbb{S}_N[y_i(\cdot)] + \mathsf{d}$$

with boundary condition  $d_{N+1} = 0$ 

• Residual update is:

$$\mathbb{S}_N[r_i(\cdot)] \leftarrow \mathbb{S}_N[r_i(\cdot)] - (\Xi + \mathbf{I}_{N+1})\mathbf{d}$$

Leads to:

$$\min_{\mathbf{d}} \|\mathbb{S}_N[r_i(\cdot)] - (\Xi + \mathbf{I}_{N+1})\mathbf{d}\|_2 \text{ s.t. } d_{N+1} = 0.$$

Solution is

$$\mathbf{d} = \begin{pmatrix} \Xi_1^+ \mathbb{S}_N[r_i(\cdot)] \\ 0 \end{pmatrix}$$

- Keep a queue of violating indices. Initialize with seed.
- In each iteration,
  - pop an index i
  - Update  $\mathbf{y}_i \equiv \mathbb{S}_N[y_i(\cdot)]$  and  $\mathbf{r}_i \equiv \mathbb{S}_N[r_i(\cdot)]$
  - Update  $\mathbf{r}_j \equiv \mathbb{S}_N[r_j(\cdot)]$  for neighboring js
  - If any violate: add to queue
- Most of the  $\mathbf{y}_i$  and  $\mathbf{r}_i$  are zero; do not keep in memory
- Only access to graph is via degree and adjacency queries
- Discounting hash operations, and with some preprocessing,  $O(N^2 + deg \cdot N)$  per iteration.

## Summary of Experimental Results

- Alg. tends to produce smaller communities (so presumably more realistic), with slightly higher conductance.
- Different results even when  $\alpha = 1.0$  (hk) and  $\gamma \rightarrow \infty$  (ppr)
  - There are many vectors that are "good enough" approx
- Comparable results to **hkgrow** (Kloster & Gleich, 2014) on datasets with ground truth.
- Running time:
  - Slower than **hkgrow** for heat-kernel ( $\alpha = 1.0$ )
  - Faster with non-degenerate parameters (e.g.  $\gamma = 5.0, \alpha = 0.85$ ).
- Fewer access to edge lists important for out-of-core.

#### Conclusions

- Efficient local algorithm for Time Dependent PageRank
- Also another local algorithm for PageRank and heat kernel.
- Experimentally, rankings that are distinct and competitive, thus a useful addition to the toolset
- Core technique: local solution of system of ODEs. Other uses?

- Open question: improved approximation bounds using time-dependent PageRank?
  - It generalizes both PageRank and heat kernel...