

CSC5420

Computer System Performance Evaluation

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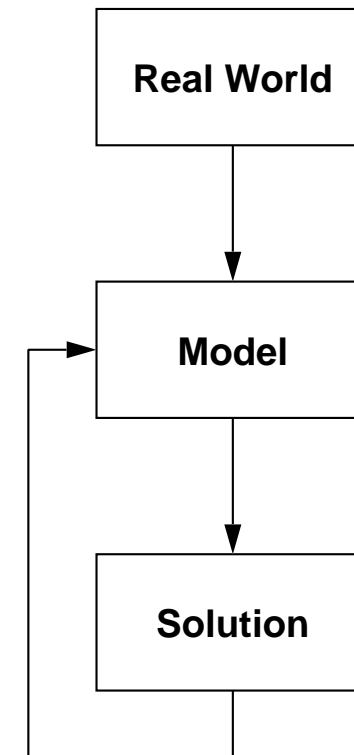
Introduction

- ▢ **Material from lectures (ref. books on web page)**
- ▢ **Grading**
 - **homework for students' benefit (will include use of software-tools on web page)**
 - **10% homework**
 - **40% projects**
 - **50% final exam**



Course Material

- ▢ Review of Probability, R.V., Transforms
- ▢ Intro. to Stoch. process (m.c.'s)
- ▢ Baby queuery theory m/m/1...
- ▢ Intermediate queuery theory m/g/1...
- ▢ Markovian model is a special structure
 - Appr. Tech.
 - Stoch. Couple
 - Matrix geometric structure
- ▢ Sample Path Analysis
- ▢ Transient Analysis
- ▢ Reversibility
- ▢ Queuery Networks - product form
- ▢ Simulation
- ▢ Measurements



- ▢ **Project: List to choose from, FCFS**
- ▢ **MS Comp: Final**

Combinatorics

▢ Permutations

- **k -permutation of a set of n elements**

$$\Rightarrow n(n-1)\cdots(n-k+1) = \frac{n!}{(n-k)!}$$

▢ Combinations

- **k -combination of a set of n elements**

➡ **k -permutation / $k!$**

$k!$ is the number of possible ways to permute that combination

$$\Rightarrow \binom{n}{k} = \frac{n!}{k!(n-k)!}$$

Combinatorics (Cont...)

Binomial Coefficients:

$$\Rightarrow \binom{n}{k} = \binom{n}{n-k}$$

Binomial Expansion:

$$\Rightarrow (x + y)^n = \sum_{k=0}^n \binom{n}{k} x^k y^{n-k}$$

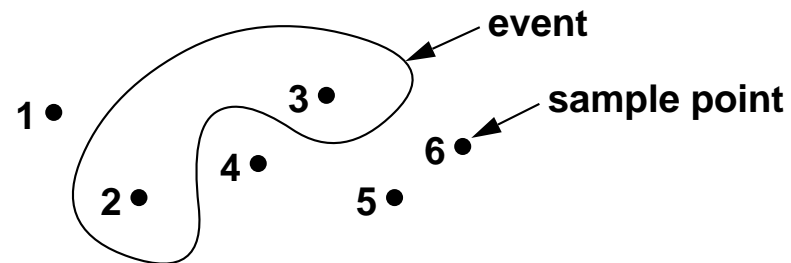
Probability

- ⇒ **Sample Space (S)**, collection of objects, where each object is a sample point.
- ⇒ **A family of events**, $\Sigma = \{A, B, C, \dots\}$ where an event is a set of sample points.
- ⇒ **A probability measure P** is an assignment (mapping) of events defined on S into real numbers (which has properties or axioms).
 - $P[A]$ = Probability of event A



Probability

- ▢ S = sample space = set whose elements are *elementary events* (possible outcome of an experiment)
 - The *elementary events* are points in a sample space (1 or more dimensions), and they are *mutually exclusive*
 - Ex: flipping a coin, a elementary events (sample points) H, T
 - *Event*: subset of sample points
 - ◇ Ex: toss dice



Probability (Cont...)

⇒ Axioms of Probability:

○ A **probability distribution** $Pr\{\}$ on a sample space S is a mapping from events of S to real numbers s.t. the following **probability axioms** hold:

- 1) $Pr\{A\} \geq 0$ for any event A (where $Pr\{A\} \equiv$ probability of event A)
- 2) $Pr\{S\} = 1$
- 3) $Pr\{A \cup B\} = Pr\{A\} + Pr\{B\}$ for events A and B that are **mutually exclusive**

$$\Rightarrow Pr\left\{\bigcup_i A_i\right\} = \sum_i Pr\{A_i\}$$

Probability (Cont...)

⇒ Things that follow:

a) $A \subseteq B \Rightarrow Pr\{A\} \leq Pr\{B\}$

b) $Pr\{\emptyset\} = 0$

c) $\bar{A} \equiv S - A \Rightarrow Pr\{\bar{A}\} = 1 - Pr\{A\}$

d) for any A, B

$$\begin{aligned} \Rightarrow Pr\{A \cup B\} &= Pr\{A\} + Pr\{B\} - Pr\{A \cap B\} \\ &\leq Pr\{A\} + Pr\{B\} \end{aligned}$$

Discrete Probability Distribution

⇒ Probability distribution is discrete if it is defined over a finite or countably infinite sample space

⇒ $Pr\{A\} = \sum_{x \in A} Pr\{x\}$ if x 's are *mutually exclusive* events in A

⇒ If S is finite and event elementary event in S has probability

$$Pr\{x\} = \frac{1}{|S|}$$

then we have the *uniform distribution* on S (or we pick an element of S at random)

Discrete Probability Distribution (Cont...)

— Ex: flipping a fair coin, $Pr\{H\} = Pr\{T\} = 0.5$

flip coin n times

$A = \{\text{exactly } k \text{ heads and exactly } n-k \text{ tails}\}$

$$\Rightarrow A \subseteq S \Rightarrow |A| = \binom{n}{k} = Pr\{A\} = \binom{n}{k} \cdot \left(\frac{1}{2}\right)^n$$

since each outcome $(s \in A) = \left(\frac{1}{2}\right)^n$

Continuous Uniform Probability Distribution

- Defined over closed interval $[a,b]$ of reals where $a < b$
 - ◆ (all subsets here, not events)
 - ⇒ want each point in $[a,b]$ to be equally likely
 - ⇒ but, infinite number of points, if give each one finite probability, will not be able to satisfy axioms 2 and 3
 - ⇒ associate probability with **some** of the subsets
- for any closed interval $[c,d]$, $a \leq c \leq d \leq b$,
continuous uniform probability distribution:

$$Pr\{[c, d]\} = \frac{d - c}{b - a}$$

$$(Pr\{[c, d]\} = Pr\{(c, d)\}, \text{ since } Pr\{[x, x]\} = Pr\{x\} = 0)$$



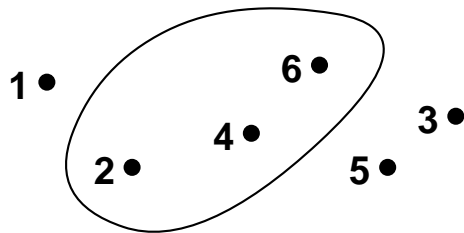
Conditional Probabilities and Independence

— **Def'n:** $Pr\{A|B\} = \frac{Pr\{A \cap B\}}{Pr\{B\}}$ whenever $Pr\{B\} \neq 0$

normalizing (sum to 1)

constrained sample space,
so we scale up

— **Ex:**



$$P[x \leq 4|B] = \frac{2}{3} = \frac{\frac{1}{6} + \frac{1}{6}}{\frac{1}{2}}$$

Conditional Probabilities and Independence (Cont...)

- ⇒ A and B are *statistically independent* if and only if:

$$Pr\{A \cap B\} = Pr\{A\} \cdot Pr\{B\}$$

- ⇒ If A_1, A_2, \dots, A_n are statistically independent

$$\Rightarrow P[A_1 \cap A_2 \cap \dots \cap A_n] = \prod_{i=1}^n P[A_i]$$

- ⇒ Also, if A and B are statistically independent, then

$$P[A|B] = \frac{P[AB]}{P[B]} = P[A]$$

Theorem of Total Probability

$$P[B] = \sum_{i=1}^n P[B|A_i] P[A_i]$$

↑ more useful form

where $\{A_i\}$ is a set of mutually exclusive exhaustive events

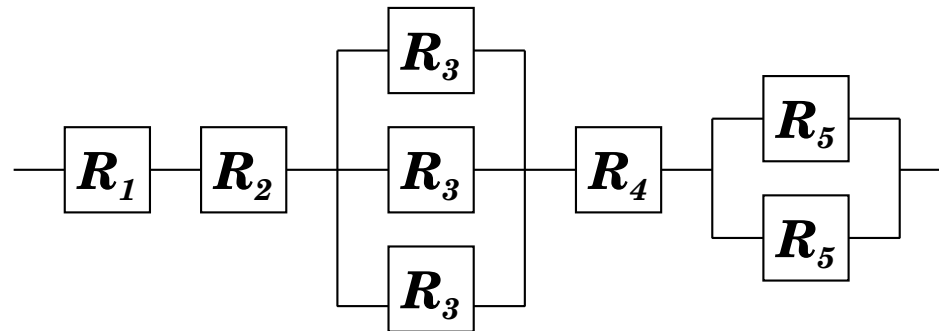
$$P[B] = \sum_{i=1}^n P[A_i B] \left\{ \begin{array}{l} \text{if occurs, occurs with exactly} \\ \text{1 mutually exclusive exhaustive} \\ \text{event } (A_i) \end{array} \right.$$

using conditional probability:

$$P[A_i B] = P[A_i|B] P[B] = P[B|A_i] P[A_i]$$

Theorem of Total Probability (Cont...)

Ex: reliability



$$R_{sys} = R_1 \cdot R_2 \cdot \left(1 - (1 - R_3)^3\right) \cdot R_4 \cdot \left(1 - (1 - R_5)^2\right)$$

where $\{R_i\}$ is the reliability of component i

Importance of Theorem of Total Probability is to break a complex problem into many *simpler problems*

Bayes' Theorem

- Look at problem from another perspective
- Assume we know event B has occurred, but we want to find which mutually exclusive event has occurred

$$P[A_i|B] = \frac{P[B|A_i] P[A_i]}{\sum_{j=1}^n P[B|A_j] P[A_j]}$$

$$P[A \cdot B] = P[B] \cdot P[A|B] = P[A] \cdot P[B|A]$$

$$P[A|B] = \frac{P[A] \cdot P[B|A]}{P[B]}$$

$$P[B] = P[B \cdot A] + P[B \cdot \bar{A}] = P[A] \cdot P[B|A] + P[\bar{A}] \cdot P[B|\bar{A}]$$

$$\Rightarrow P[A|B] = \frac{P[A] \cdot P[B|A]}{P[A] \cdot P[B|A] + P[\bar{A}] \cdot P[B|\bar{A}]}$$

└──────────▶ more general form above

Bayes' Theorem (Cont...)

More general forms:

$A_i, 1 \leq i \leq n$, are mutually exclusive, exhaustive events

Theorem of total probability $\Rightarrow P[B] = \sum_{i=1}^n P[B|A_i] \cdot P[A_i]$

Bayes' Theorem $\Rightarrow P[A_i|B] = \frac{P[B|A_i] \cdot P[A_i]}{\sum_{j=1}^n P[B|A_j] \cdot P[A_j]}$

Example

⇒ Ex: gambling, $D_H \Leftarrow$ honest dealer, $D_C \Leftarrow$ cheating dealer

$L \Leftarrow$ you lose

play honest dealer \Rightarrow lose with prob = $1/2$

play cheating dealer \Rightarrow lose with prob = p

(of $p > 1/2$ against you, of $p < 1/2$ for you)

$$\begin{aligned} P[D_C|L] &= \frac{P[L|D_C] \cdot P[D_C]}{P[L|D_C] \cdot P[D_C] + P[L|D_H] \cdot P[D_H]} \\ &= \frac{p \cdot \frac{1}{2}}{p \cdot \frac{1}{2} + \left(\frac{1}{2}\right) \left(\frac{1}{2}\right)} = \frac{2p}{2p + 1} \end{aligned}$$

⇒ if $p=1$, prob. that cheating dealer if lost 1 game = $2/3$

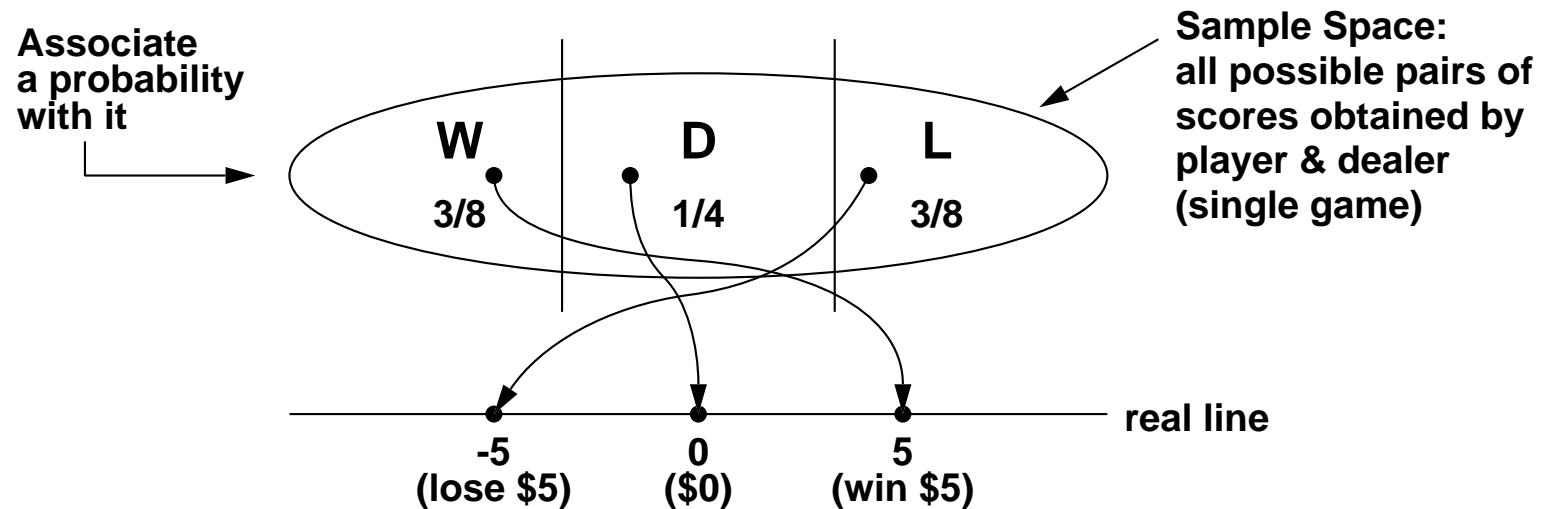
Random Variables (R.V.)

- ⇒ We have the probability system (S, Σ, P)
- ⇒ R.V. is a variable whose value depends upon the outcome of the random experiment
- ⇒ The *outcome* of a random experiment is $w \in S$
 - We associate a real number $X(w)$ with W
- ⇒ Thus our r.v. $X(W)$ is nothing more than a function defined on the sample space S
 - i.e., a function from a finite or countably infinite sample space S to real numbers



Example

- Ex: playing a game of black jack in Las Vegas



- Notation: R.V. X on a sample S

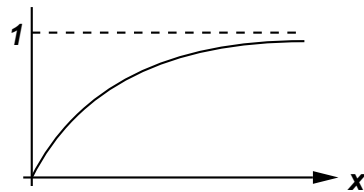
$$X : S \rightarrow R$$

$\rightarrow X(w)$ - our winnings on a single game of black jack

$$X(w) = \begin{cases} +5 & w \in W \\ 0 & w \in D \\ -5 & w \in L \end{cases}$$

Discrete Random Variables

- ▢ Discrete Random Variables: (X)
 - a function from a finite (or countably infinite) sample space S to real numbers
 - ◇ interested in functions of events
 - ⇒ each outcome is a combination of events, so we can assign probability to it
 - $P[X \leq x]$: probability distribution function



Discrete Random Variable (Cont...)

$$Pr \{X = x\} = \sum_{s \in S; X(s)=x} Pr \{s\}$$

$f(x) = Pr \{X = x\} \Rightarrow$ probability mass function of X

$$\Rightarrow Pr \{X = x\} \geq 0, \sum_x Pr \{X = x\} = 1$$

$$f(x, y) = Pr \{X = x \text{ and } Y = y\}$$

is the joint probability mass function of X and Y

$$Pr \{Y = y\} = \sum_x Pr \{X = x \text{ and } Y = y\}$$

$$Pr \{X = x\} = \sum_y Pr \{X = x \text{ and } Y = y\}$$

$$Pr \{X = x | Y = y\} = \frac{Pr \{X = x \text{ and } Y = y\}}{Pr \{Y = y\}}$$

X and Y are independent if $\forall x, y :$

$$Pr \{X = x \text{ and } Y = y\} = Pr \{X = x\} \cdot Pr \{Y = y\}$$

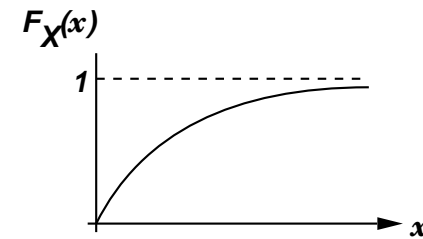


Expectation, Variance, and Standard Deviation

$$E[X] = \sum_x x \cdot Pr\{X = x\}$$

$$E[X + Y] = E[X] + E[Y]$$

$$E[g(X)] = \sum_x g(x) \cdot Pr\{X = x\}$$



if X and Y are independent, then $E[XY] = E[X]E[Y]$

if X takes on rational numbers $N = \{0, 1, 2, \dots\}$

$$\Rightarrow E[X] = \sum_{i=0}^{\infty} i \cdot Pr\{X = i\} = \sum_{i=1}^{\infty} Pr\{X \geq i\}$$

$$\sigma_X^2 = Var[X] = E[(X - E[X])^2] = E[X^2] - (E[X])^2$$

$$\text{standard deviation} = \sqrt{Var[X]} = \sigma_X$$

if X and Y are independent $\Rightarrow Var[X + Y] = Var[X] + Var[Y]$

Probability Distribution Function (PDF) or Cumulative Distribution Function

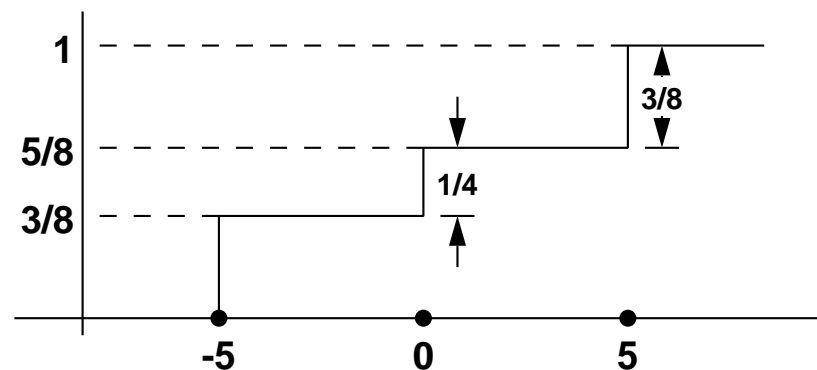
$$[X \leq x] \equiv \{w : X(w) \leq x\}$$

PDF is defined as $F_X(x) = P[X \leq x]$

Properties:

- 1) $F_X(x) \geq 0$
- 2) $F_X(\infty) = 1$
- 3) $F_X(-\infty) = 0$
- 4) $F_X(b) - F_X(a) = P[a < X \leq b]$ for $a < b$
- 5) $F_X(b) \geq F_X(a)$ for $a \leq b$

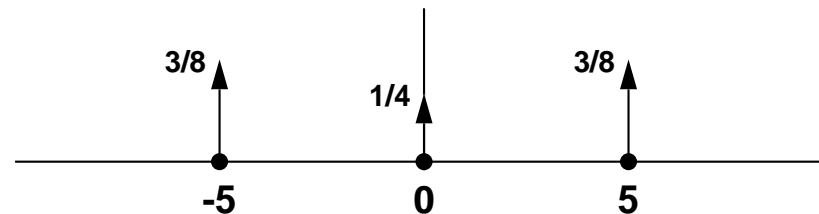
Ex: PDF for the Las Vegas Game



Probability Density Function (pdf) or Probability Mass Function (pmf)

$$f_X = \frac{dF_X(x)}{dx}$$

⇒ Ex: pdf for the blackjack game



Different ways to view pdf:

- 1) $F_X(x) = \int_{-\infty}^x f_X(y)dy$
- 2) $f_X(x) \geq 0$
- 3) $\int_{-\infty}^{\infty} f_X(x)dx = 1$
- 4) $P[a < X \leq b] = \int_a^b f_X(x)dx$

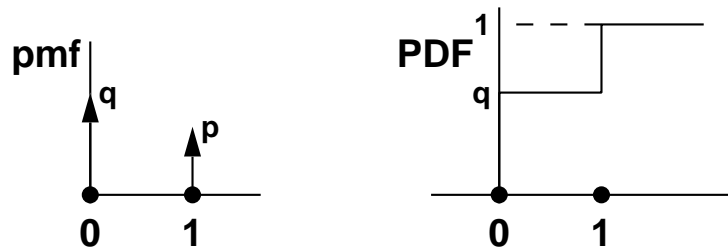


Special Discrete Distribution

▢ The Bernoulli pmf

$$P_X(0) = P[X = 0] = q$$

$$P_X(1) = P[X = 1] = p = (1 - q)$$



Geometric Distribution

▬ Bernoulli trial:

- experiment with only 2 possible outcomes
 - ◇ success with probability p
 - ◇ failure with probability $q = 1-p$
- Bernoulli trials, a sequence of *independent* trials each with probability p

⇒ r.v. X = number of trials needed to obtain success

$$X \in \{1, 2, \dots\}$$

for $k \geq 1$, $Pr\{X = k\} = q^{k-1}p = (1-p)^{k-1} \cdot p$

⇒ **geometric distribution**

assume $p \leq 1$, $\Rightarrow E[X] = \frac{1}{p} = \sum_{k=1}^{\infty} k \cdot (1-p)^{k-1} \cdot p$

⇒ **on average, $1/p$ trials before obtain success**

$$\sigma_X^2 = \frac{1-p}{p^2}$$



Binomial Distribution

⇒ r.v. X = number of successes in n trials, $X \in \{0, 1, \dots\}$

$$\text{for } k = 0, 1, \dots, n, Pr\{X = k\} = \binom{n}{k} p^k (1 - p)^{n-k}$$

⇒ **binomial distribution**

$$E[X] = np, \sigma_X^2 = np(1 - p)$$

Multiple R.V.

- ⇒ Can, of course, define many r.v. on same sample space
- ⇒ Let X & Y be 2 r.v. on some probability system (S, Σ, P)
- ⇒ Natural extension of PDF:

$$F_{XY}(x, y) \equiv P[X \leq x, Y \leq y]$$

⇒ **joint PDF**

- ⇒ **Joint probability density function:**

$$f_{XY}(x, y) \equiv \frac{d^2 F_{XY}(x, y)}{dxdy}$$

- ⇒ **Marginal density function (for one of the variables):**

$$f_X(x) = \int_{y=-\infty}^{\infty} f_{XY}(x, y) dy$$

(given by integrating over all possible values of the 2nd variable)



Multiple R.V. (Cont...)

- ⇒ Notion of *independence* between r.v.'s
 - X & Y are independent iff: (same for more than 2 variables)

$$f_{XY}(x, y) = f_X(x) \cdot f_Y(y)$$

- ⇒ Can also define one random variable in terms of another, i.e.,

$$y = g(x)$$

$$\Rightarrow F_Y = P[Y \leq y] = P[\{w : g(X(w)) \leq y\}] \leftarrow$$

(could be complex computation)

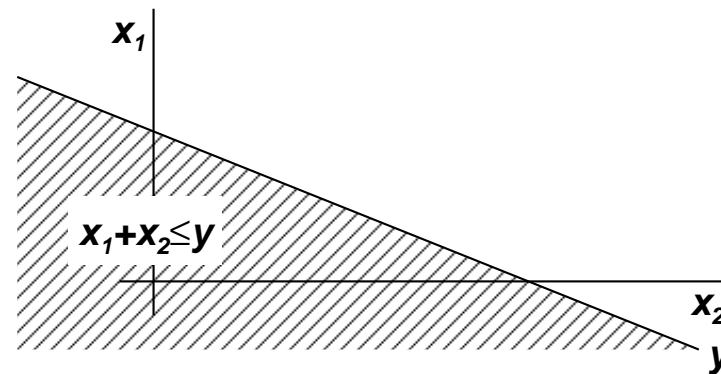
- ⇒ Of course, can be a function of many r.v.

Example

- Ex: Let $Y = X_1 + X_2$ (i.e., sum of 2 r.v.)
where X_1 and X_2 are *independent*

$$\Rightarrow F_Y(y) = P[Y \leq y] = P[X_1 + X_2 \leq y]$$

$$F_Y(y) = \int_{-\infty}^{\infty} \int_{-\infty}^{y-x_2} f_{X_1 X_2}(x_1, x_2) dx_1 dx_2$$



Example (Cont...)

⇒ due to independence:

$$\begin{aligned} F_Y(y) &= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{y-x_2} f_{X_1}(x_1) dx_1 \right] f_{X_2}(x_2) dx_2 \\ &= \int_{-\infty}^{\infty} F_{X_1}(y-x_2) f_{X_2}(x_2) dx_2 \end{aligned}$$

$$\Rightarrow f_Y(y) = \underbrace{\int_{-\infty}^{\infty} f_{X_1}(y-x_2) f_{X_2}(x_2) dx_2}_{\text{convolution of density functions of } X_1 \text{ and } X_2}$$

convolution of density functions of X_1 and X_2

$$\Rightarrow f_Y(y) = f_{X_1}(y) \otimes f_{X_2}(y)$$

(same for any n sum of independent r.v.)



Expectation

⇒ The **expectation** of a real r.v. $X(\omega)$ is denoted by $E[X]$

⇒ also denoted by \bar{X}

$$E[X] \equiv \bar{X} \equiv \int_{-\infty}^{\infty} x dF_X(x)$$

$$E[X] = \bar{X} = \int_{-\infty}^{\infty} x f_X(x) dx$$

$$E[X] = \int_0^{\infty} [1 - F_X(x)] dx - \int_{-\infty}^0 F_X(x) dx \longrightarrow \text{Stieltjes Integral}$$

⇒ For X , a nonnegative r.v.

$$E[X] = \int_0^{\infty} [1 - F_X(x)] dx \quad x \geq 0$$



Fundementation Theorem of Expectation

⇒ Let $y=g(x)$

$$E_Y [Y] = \int_{-\infty}^{\infty} y f_Y(y) dy \quad \text{could be complex to compute } f_Y(y)$$

⇒ **Fundementation Theorem of Expectation:**

$$E_Y [Y] = E_X [g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx$$

⇒ **Expectation of sum of 2 r.v.**

$$\begin{aligned} E[X + Y] &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} (x + y) f_{XY}(x, y) dx dy \\ &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x f_{XY}(x, y) dx dy + \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} y f_{XY}(x, y) dx dy \\ &= \int_{-\infty}^{\infty} x f_X(x) dx + \int_{-\infty}^{\infty} y f_Y(y) dy \\ &= E[X] + E[Y] \end{aligned}$$

← (generalize to any number of variables)

○ **True whether or not X & Y are independent**

Product of R.V.

$$E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{XY}(x, y) dx dy$$

- If X & Y are **independent**, then

$$E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x f_X(x) y f_Y(y) dx dy = E[X] \cdot E[Y]$$

$$\Rightarrow E[g(X)h(Y)] = E[g(X)] \cdot E[h(Y)]$$

- Interested in power of r.v.'s

$$\Rightarrow E[X^n] \Rightarrow n^{\text{th}} \text{ moment of } X$$

$$\Rightarrow E[X^n] \equiv \bar{X}^n \equiv \int_{-\infty}^{\infty} x^n f_X(x) dx \quad \text{follows from the fundamental theorem of expectation}$$

$$\Rightarrow n^{\text{th}} \text{ central moment is :}$$

$$(X - \bar{X})^n \equiv \int_{-\infty}^{\infty} (x - \bar{X})^n f_X(x) dx$$

$$\Rightarrow (X - \bar{X})^n = \sum_{k=0}^n \binom{n}{k} x^k (-\bar{X})^{n-k} \quad \text{binomial theorem}$$

Product of R.V. (Cont...)

take expectation of both sides

$$\Rightarrow \overline{(X - \bar{X})^n} = \sum_{k=0}^n \binom{n}{k} \bar{x}^k (-\bar{X})^{n-k}$$

sums of expectation,
expectation of sums,
expectation of constant

$$\Rightarrow 0^{th} \text{ moment} = 1; \text{ also } 0^{th} \text{ central moment} = 1$$

$$\Rightarrow 1^{st} \text{ central moment} \Rightarrow \overline{(X - \bar{X})} = \bar{X} - \bar{X} = 0$$

$$\Rightarrow 2^{nd} \text{ central moment} \Rightarrow \text{variance}$$

$$\sigma_X^2 \equiv \overline{(X - \bar{X})^2} \equiv \overline{X^2} - (\bar{X})^2$$

$$\sigma_X \Rightarrow \text{standard deviation} = \sqrt{\sigma_X^2}$$

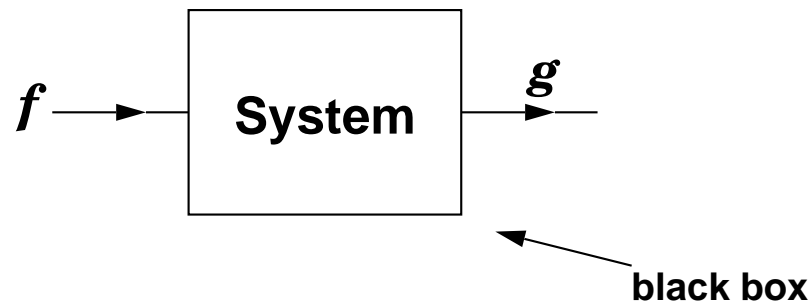
$$\Rightarrow C_X \equiv \frac{\sigma_X}{\bar{X}} \quad \text{coefficient of variation}$$

Transforms

- ➡ Transforms, characteristic function, generating function...
- ➡ Laplace, z, Fourier, ...
- ➡ When introduce into solution method, simplify calculations
- ➡ Appear naturally, why?

Linear Time-invariant Systems

systems \equiv transformations, mapping, input-output
relationship between 2 functions



assume $\Rightarrow f=f(t), f(t) \rightarrow g(t)$

Linear and Time-invariant

- ⇒ **Linear** if when $f_1(t) \rightarrow g_1(t)$ and $f_2(t) \rightarrow g_2(t)$
then also $af_1(t)+bf_2(t) \rightarrow ag_1(t)+bg_2(t)$
- ⇒ **Time-invariant** if when $f(t) \rightarrow g(t)$
then also $f(t+\tau) \rightarrow g(t+\tau)$
- ⇒ If both holds, we have a **linear time-invariant system**

↑
— we focus on these



Transforms

- ⇒ Decompose function of time into sums (integrals) of complex exponentials
 - complex exponentials form building blocks of transforms
- ⇒ *Question:* which functions of time can pass through linear time-invariant systems without change?
 - i.e., $f(t) \rightarrow g(t) = Hf(t)$, where H is some scalar multiple
 - if can find these, then can find **eigenfunctions** or **characteristic functions**, or **invariants** of our system

↳ $f_e(t) = e^{st}$ where s is a complex variable

↳ form the set of eigenfunctions for *all* linear time-invariant systems



Characteristic Functions

Derivation:

linearity $\left\{ \begin{array}{l} f_e(t) = e^{st} \rightarrow g_e(t) \\ \rightarrow e^{s\tau} f_e(t) = e^{s(t+\tau)} \rightarrow e^{s\tau} g_e(t) \end{array} \right.$

time-invariant $\left\{ \begin{array}{l} \text{where } \tau \text{ and hence } e^{s\tau} \text{ are constant} \\ \rightarrow f_e(t + \tau) = e^{s(t+\tau)} \rightarrow g_e(t + \tau) \end{array} \right.$

$$\Rightarrow e^{s\tau} g_e(t) = g_e(t + \tau)$$

unique solution $\left\{ \begin{array}{l} \rightarrow g_e(t) = H e^{st} \end{array} \right.$

$$e^{st} \rightarrow H(s) e^{st}$$

$\left\{ \begin{array}{l} \rightarrow \text{independent of } t \text{ but} \\ \text{can be function of } s \end{array} \right.$

Characteristic Functions (Cont...)

- ⇒ Overall output found by summing (integrating) these individual components of the output
 - decompose input into sums of exponentials, computing response to each as above, and then reconstituting the output from sums of exponentials is referred to as *transform* method

Transforms

Focus on discrete time first

$$f(t) = f(t = nT) \quad \text{where } n = \dots, -2, -1, 0, 1, 2, \dots$$

\downarrow
 $\rightarrow f_n$

$$\Rightarrow f_n \rightarrow g_n$$

$$af_n^{(1)} + bf_n^{(2)} \rightarrow ag_n^{(1)} + bg_n^{(2)}$$

$$f_{n+m} \rightarrow g_{n+m} \quad m \text{ is an integer constant}$$

\Rightarrow **eigenfunctions:**

$$f_n^{(e)} = e^{st} = e^{snT}$$

$$\text{Let } z \equiv e^{-sT} \Rightarrow f_n^{(e)} = z^{-n}$$

\downarrow
also a complex variable



Transforms (Cont...)

$$\Rightarrow z^{-n} \rightarrow H(z) z^{-n} \quad H(z) \text{ is independent of } n \quad (\text{t1})$$

$\Rightarrow \{z^{-n}\}$ form a set of eigenfunctions

$\Rightarrow H$ expresses how much we get out of unit input \Rightarrow system (or transfer) function

\Rightarrow **Kronecker delta function** or **unit function**:

$$u_n = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$

\Rightarrow **Unit response** (when apply u_n to system), h_n

$$u_n \rightarrow h_n$$

$$\Rightarrow u_{n+m} \rightarrow h_{n+m}$$



Transforms (Cont...)

linearity $\Rightarrow z^m u_{n+m} \rightarrow z^m h_{n+m}$

multiple by unity on both sides $\Rightarrow (z^{-n} z^n) z^m u_{n+m} \rightarrow (z^{-n} z^n) z^m h_{n+m} \quad (t2)$

⇒ Consider set of inputs $\{f_n^{(i)}\}$

$$\Rightarrow f_n^{(i)} \rightarrow g_n^{(i)}$$

linearity $\Rightarrow \sum_i f_n^{(i)} \rightarrow \sum_i g_n^{(i)} \quad \Rightarrow$ apply to Eq. (t2)

$$\Rightarrow z^{-n} \sum_m z^{n+m} u_{n+m} \rightarrow z^{-n} = \sum_m z^{n+m} h_{n+m}$$

sum over all integer value of m

→ only 1 non-zero term, when $m=-n$, and it equals 1

Transforms (Cont...)

plus change
of variables

$$\Rightarrow z^{-n} \rightarrow z^n \sum_k z^k h_k \quad (\text{go back to Eq. (t1)})$$

$$\Rightarrow H(z) = \sum_k h_k z^k$$

- ◆ related system function $H(z)$ to unit response
- ◆ both $H(z)$ and unit response describe how the system operates, so they are related
- ◆ itself a transform, a *z -Transform*
 - so transforms arise naturally

z-Transform

- ⇒ Let f_n be a function which takes on nonzero values
 - only for non-negative integers, $n=0, 1, 2, \dots$ ($f_n=0$ for $n < 0$)
- ⇒ Compress sequence into a single function such that can expand later
- ⇒ Place a tag on each term
 - i.e., tag each f_n with z^n (n unique \Rightarrow each tag is unique)
- ⇒ Define z-transform (or generating function, or geometric transform)

$$F(z) \equiv \sum_{n=0}^{\infty} f_n z^n$$

- ⇒ The z-transform will exist as long as terms don't grow any faster than geometrically, i.e., as long as a exists, s.t.

$$\lim_{n \rightarrow \infty} \frac{|f_n|}{a^n} = 0$$

z-Transform (Cont...)

⇒ Given a sequence f_n , its z-transform is unique

If sum over all f_n is finite, then $F(z)$ is analytic on $|z| \leq 1$.

Then:

$$\Rightarrow F(1) = \sum_{n=0}^{\infty} f_n$$

Notation:

$$f_n \Leftrightarrow F(z)$$

⇒ has a unique derivative at that point ⇒ function is analytic at that point



Examples of z-Transforms

▢ **Ex 1: Recall the unit function**

$$u_n = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$

⇒ Exactly 1 term in the infinite summation is non-zero

$$\Rightarrow u_n \Leftrightarrow 1$$

▢ **Ex 2: Shift the unit function to the right**

$$u_{n-k} = \begin{cases} 1 & n = k \\ 0 & n \neq k \end{cases}$$

$$\Rightarrow u_{n-k} \Leftrightarrow z^k$$

Examples of z-Transforms (Cont...)

Ex 3: unit step function

$$\delta_n = 1 \quad \text{for } n = 0, 1, 2, \dots$$

$$\delta_n \Leftrightarrow \sum_{n=0}^{\infty} 1 \cdot z^n = \frac{1}{1-z} \Rightarrow |z| < 1 \text{ for transform to exist}$$

Ex 4: geometric series

$$f_n = A\alpha^n \quad n = 0, 1, 2, \dots$$

$$\Rightarrow F(z) = \sum_{n=0}^{\infty} A\alpha^n \cdot z^n = A \sum_{n=0}^{\infty} (\alpha z)^n = \frac{A}{1-\alpha z}$$

$$A\alpha^n \Leftrightarrow \frac{A}{1-\alpha z} \quad \left(\text{where } |z| < \frac{1}{\alpha}\right)$$

region of
analycity

Properties of z-Transforms

Convolution property

- We have 2 function, f_n and g_n with $f_n \Leftrightarrow F(z)$ and $g_n \Leftrightarrow G(z)$

$$f_n \otimes g_n \equiv \sum_{k=0}^n f_{n-k} g_k$$

$$\Rightarrow f_n \otimes g_n \Leftrightarrow \sum_{n=0}^{\infty} (f_n \otimes g_n) z^n = \sum_{n=0}^{\infty} \sum_{k=0}^n f_{n-k} g_k z^{n-k} z^k$$

$$\text{since } \sum_{n=0}^{\infty} \sum_{k=0}^n = \sum_{k=0}^{\infty} \sum_{n=k}^{\infty}$$

$$\begin{aligned} \Rightarrow f_n \otimes g_n \Leftrightarrow \sum_{k=0}^{\infty} g_k z^k \cdot \sum_{n=k}^{\infty} f_{n-k} z^{n-k} &= \left(\sum_{k=0}^{\infty} g_k z^k \right) \left(\sum_{m=0}^{\infty} f_m z^m \right) \\ &= G(z) \cdot F(z) \end{aligned}$$

$$f_n \otimes g_n \Leftrightarrow G(z) \cdot F(z)$$

Other Properties of z-Transforms

$$\Rightarrow af_n + bg_n \Leftrightarrow aF(z) + bG(z) \longrightarrow \text{linearity}$$

$$\left[\begin{array}{l} \Rightarrow a^n f_n \Leftrightarrow F(az) \\ \Rightarrow f_n/k \ (n = 0, k, 2k, \dots) \Leftrightarrow F(z^k) \end{array} \right\} \text{scale change in the} \\ \text{transform and time domains}$$

$$\Rightarrow f_{n+1} \Leftrightarrow \frac{1}{z} [F(z) - f_0]$$

$$f_{n+k} \ (k > 0) \Leftrightarrow \frac{F(z)}{z^k} - \sum_{i=1}^k z^{i-k-1} f_{i-1}$$

$$\Rightarrow f_{n-1} \Leftrightarrow zF(z)$$

advance or delay
by unit of time
results in divide
or multiply in
transform domain

Inverse Transforms

⇒ Given $F(z)$, find sequence f_n

○ Power series method, e.g.,

$$f_n = \left. \frac{1}{n!} \frac{d^n F(z)}{dz^n} \right|_{z=0}$$

◇ not as useful if want many terms

⇒ ratio of numerators and denominators

○ Inspection method

◇ express $F(z)$ in terms which have recognizable transform pairs

◇ *partial-fraction expansion*



Inverse Transforms (Cont...)

◆ e.g., each term is either

1) a simple pole $\longrightarrow A\alpha^n \Leftrightarrow \frac{A}{1 - \alpha z}$

2) a multiple pole

$$\longmapsto \frac{1}{m!} (n+m)(n+m-1) \cdots (n+1) \alpha^n \Leftrightarrow \frac{1}{(1 - \alpha z)^{m+1}}$$

in addition, sum of transforms is transform of sums

$$\Rightarrow F(z) = \frac{N(z)}{D(z)} \quad \text{where } N(z) + D(z) \text{ are polynomials in } z$$

and degree of $N(z) <$ degree of $D(z)$

also $\Rightarrow D(z)$ is in factored form

$$D(z) = \prod_{i=1}^k (1 - \alpha_i z)^{m_i}$$

$\longmapsto i^{\text{th}}$ root at $z = \frac{1}{\alpha_i}$ and it's of multiplicity m_i

\longrightarrow **factoring could be the hard part**

Inverse Transforms (Cont...)

$$\begin{aligned} \Rightarrow F(z) &= \frac{A_{11}}{(1 - \alpha_1 z)^{m_1}} + \frac{A_{12}}{(1 - \alpha_1 z)^{m_1-1}} + \cdots + \frac{A_{1m_1}}{(1 - \alpha_1 z)} \\ &+ \frac{A_{21}}{(1 - \alpha_2 z)^{m_2}} + \frac{A_{22}}{(1 - \alpha_2 z)^{m_2-1}} + \cdots + \frac{A_{2m_2}}{(1 - \alpha_2 z)} \\ &+ \cdots \\ &+ \frac{A_{k1}}{(1 - \alpha_k z)^{m_k}} + \frac{A_{k2}}{(1 - \alpha_k z)^{m_k-1}} + \cdots + \frac{A_{km_k}}{(1 - \alpha_k z)} \end{aligned}$$

use known
transform

$$\hookrightarrow \sum_{k=0}^n f_k \Leftrightarrow \frac{F(z)}{1-z} x^2 \quad (n = 0, 1, 2, \dots)$$

$$\Rightarrow A_{ij} = \frac{1}{(j-1)!} \left(\frac{-1}{\alpha_i} \right)^{j-1} \frac{d^{j-1}}{dz^{j-1}} \left[(1 - \alpha_i z)^{m_i} \frac{N(z)}{D(z)} \right] \Bigg|_{z=\frac{1}{\alpha_i}}$$

Example

$$F(z) = \frac{4z^2(1 - 8z)}{(1 - 4z)(1 - 2z)^2}$$

⇒ **need numerator power < denominator power**

$$\text{Let } G(z) = \frac{4(1 - 8z)}{(1 - 4z)(1 - 2z)^2}$$

⇒ **2 poles:**

- 1)** $z = \frac{1}{4}$
- 2)** $z = \frac{1}{2}$ ← **two poles here**

⇒ $k = 2, \alpha_1 = 4, m_1 = 1, \alpha_2 = 2, m_2 = 2$

Example (Cont...)

$$\begin{aligned} \Rightarrow G(z) &\equiv \frac{4(1-8z)}{(1-4z)(1-2z)^2} \\ &= \frac{A_{11}}{(1-4z)} + \frac{A_{21}}{(1-2z)^2} + \frac{A_{22}}{(1-2z)} \end{aligned}$$

ungroup previous equation

$$\begin{aligned} \rightarrow A_{11} &= (1-4z)G(z)\Big|_{z=\frac{1}{4}} = \frac{4(1-\frac{8}{4})}{(1-\frac{2}{4})^2} = -16 \\ \rightarrow A_{21} &= (1-2z)^2 G(z)\Big|_{z=\frac{1}{2}} = \frac{4(1-\frac{8}{2})}{(1-\frac{4}{2})} = 12 \\ \rightarrow A_{22} &= -\frac{1}{2} \frac{d}{dz} \left[(1-2z)^2 G(z) \right] \Big|_{z=\frac{1}{2}} = -\frac{1}{2} \frac{d}{dz} \frac{4(1-8z)}{(1-4z)} \Big|_{z=\frac{1}{2}} \\ &= -\frac{4}{2} \frac{(1-4z)(-8) - (1-8z)(-4)}{(1-4z)^2} \Big|_{z=\frac{1}{2}} = 8 \end{aligned}$$

$$\Rightarrow G(z) = \frac{-16}{(1-4z)} + \frac{12}{(1-2z)^2} + \frac{8}{(1-2z)}$$

Example (Cont...)

by inspection

$$\Rightarrow G(z) \Leftrightarrow g_n = \begin{cases} 0 & n < 0 \\ -16(4)^n + 12(n+1)(2)^n + 8(2)^n & n = 0, 1, 2, \dots \end{cases}$$

\Rightarrow **need to account for** z^2

$$\Rightarrow k > 0, f_{n-k} \Leftrightarrow z^k F(z)$$

$$\Rightarrow f_n = -16(4)^{n-2} + 12(n-1)(2)^{n-2} + 8(2)^{n-2}$$

$$\Rightarrow f_n = \begin{cases} 0 & n < 2 \\ (3n-1)2^n - 4^n & n = 2, 3, 4, \dots \end{cases}$$



Laplace Transform

- ⇒ Consider function of continuous time $f(t)$, $f(t) = 0$, for $t < 0$
- ⇒ As before, want to transform from a function of t to a function of a complex variable s , and also want to be able to "untransform", so want "tag" each value $f(t)$
- ⇒ use e^{-st} as our tag
- ⇒ $s = \sigma + j\omega$ where $j = \sqrt{-1}$

$$\Rightarrow F^*(s) \equiv \int_{-\infty}^{\infty} f(t) e^{-st} dt$$

since
assume
 $f(t) = 0$
for $t < 0$

$$\Rightarrow F^*(s) = \int_0^{\infty} f(t) e^{-st} dt$$

0^- → any accumulation at origin (e.g., impulse function) will be included

⇒ Exists as long as $f(t)$ grown no faster than exponential, i.e., there is some real number σ_a s.t.

$$\lim_{\tau \rightarrow \infty} \int_0^{\tau} |f(t)| e^{-\sigma_a t} dt < \infty$$

Laplace Transform (Cont...)

- ⇒ Laplace transform for a given $f(t)$ is unique
- ⇒ If integral of $f(t)$ is finite, then $\text{Re}(s) > 0$ represents region of analyticity for $F^*(s)$

$$\Rightarrow F^*(0) = \int_0^{\infty} f(t) dt \quad (z = 1 \text{ corresponds to } s = 0)$$

- ⇒ Use notation:

$$f(t) \Leftrightarrow F^*(s)$$

- ⇒ Inverse by inspection

Examples of Laplace Transforms

Ex 1:
$$f(t) = \begin{cases} A e^{-at} & t \geq 0 \\ 0 & t < 0 \end{cases}$$

$$f(t) \Leftrightarrow F^*(s) = \int_0^{\infty} A e^{-at} e^{-st} dt = A \int_0^{\infty} e^{-(s+a)t} dt$$

$$= \frac{A}{s+a}$$

$$\Rightarrow A e^{-at} \delta(t) \Leftrightarrow \frac{A}{s+a}$$

where $\delta(t) = \begin{cases} 1 & t \geq 0 \\ 0 & t < 0 \end{cases}$ **unit step function in continuous time
(to get $f(t)$ defined above)**

Ex 2: if $A = 1, a = 0 \Rightarrow$ have unit step function

$$\Rightarrow \delta(t) \Leftrightarrow \frac{1}{s}$$

Inspection Method

⇒ Assume $F^*(s)$ is a rational function of s , i.e.,

$$F^*(s) = \frac{N(s)}{D(s)}$$

where $N(s)$ and $D(s)$ are polynomials in s
degree of $N(s)$ < degree of $D(s)$

⇒ factor $D(s)$

$$D(s) = \prod_{i=1}^k (s + a_i)^{m_i}$$

Inspection Method (Cont...)

$$\begin{aligned} \Rightarrow F^*(s) = & \frac{B_{11}}{(s+a_1)^{m_1}} + \frac{B_{12}}{(s+a_1)^{m_1-1}} + \cdots + \frac{B_{1m_1}}{(s+a_1)} \\ & + \frac{B_{21}}{(s+a_2)^{m_2}} + \frac{B_{22}}{(s+a_2)^{m_2-1}} + \cdots + \frac{B_{2m_2}}{(s+a_2)} \\ & + \cdots \\ & + \frac{B_{k1}}{(s+a_k)^{m_k}} + \frac{B_{k2}}{(s+a_k)^{m_k-1}} + \cdots + \frac{B_{km_k}}{(s+a_k)} \end{aligned} \quad \left. \vphantom{\frac{B_{11}}{(s+a_1)^{m_1}}} \right\} \text{from table}$$

$$\text{where } B_{ij} = \frac{1}{(j-1)!} \left. \frac{d^{j-1}}{ds^{j-1}} \left[(s+a_i)^{m_i} \frac{N(s)}{D(s)} \right] \right|_{s=-a_i}$$



Example

$$F^*(s) = \frac{8(s^2 + 3s + 1)}{(s + 3)(s + 1)^3}$$

$$\Rightarrow k = 2, \quad a_1 = 3, m_1 = 1, \quad a_2 = 1, m_2 = 3$$

$$\Rightarrow F^*(s) = \frac{B_{11}}{(s + 3)} + \frac{B_{21}}{(s + 1)^3} + \frac{B_{22}}{(s + 1)^2} + \frac{B_{23}}{(s + 1)}$$

$$B_{11} = (s + 3)F^*(s)|_{s=-3} = \frac{8(9 - 9 + 1)}{(-2)^3} = -1$$

$$B_{21} = (s + 1)^3 F^*(s)|_{s=-1} = \frac{8(1 - 3 + 1)}{(2)} = -4$$

$$\begin{aligned} B_{22} &= \left. \frac{d}{ds} \left[\frac{8(s^2 + 3s + 1)}{(s + 3)} \right] \right|_{s=-1} \\ &= 8 \left. \frac{(s + 3)(2s + 3) - (s^2 + 3s + 1)(1)}{(s + 3)^2} \right|_{s=-1} \end{aligned}$$



Example (Cont...)

$$= 8 \left[\frac{s^2 + 6s + 8}{(s + 3)^2} \right] \Big|_{s=-1} = 8 \left[\frac{1 - 6 + 8}{(2)^2} \right] = 6$$

already took this derivative

$$B_{23} = \frac{1}{2!} \frac{d^2}{ds^2} \left[\frac{8(s^2 + 3s + 1)}{(s + 3)} \right] \Big|_{s=-1} = \frac{8}{2} \frac{d}{ds} \left[\frac{(s^2 + 6s + 8)}{(s + 3)^2} \right] \Big|_{s=-1}$$

$$= 4 \frac{(s + 3)^2(2s + 6) - (s^2 + 6s + 8)(2)(s + 3)}{(s + 3)^4} \Big|_{s=-1}$$

$$= 4 \frac{(2)^2(4) - (1 - 6 + 8)(2)(2)}{(2)^4} = 1$$

$$\Rightarrow F^*(s) = \frac{-1}{(s + 3)} + \frac{-4}{(s + 1)^3} + \frac{6}{(s + 1)^2} + \frac{1}{(s + 1)}$$

using table

$$\Rightarrow f(t) = -e^{-3t} - 2t^2e^{-t} + 6te^{-t} + e^{-t}$$

$$\text{and } f(t) = 0 \text{ for } t < 0$$

Difference Equations

⇒ ***N*th order difference equation:** (standard method)

$$a_N g_{n-N} + a_{N-1} g_{n-N+1} + \cdots + a_0 g_n = e_n$$

where a_i are the known constants and

g_i are the unknown functions to be found, and

e_n is a given function of n

plus we are given N bounding equations

⇒ as usual, solution has homogeneous and particular part:

$$g_n = g_n^{(h)} + g_n^{(p)}$$

⇒ homogeneous solution must satisfy homogeneous equation:

$$a_N g_{n-N} + a_{N-1} g_{n-N+1} + \cdots + a_0 g_n = 0$$

⇒ general form of solution is:

$$g_n^{(h)} = A \alpha^n$$

where A and α are to be determined

$$\Rightarrow a_N A \alpha^{n-N} + a_{N-1} A \alpha^{n-N+1} + \cdots + a_0 A \alpha^n = 0$$



Difference Equations (Cont...)

⇒ ***N*th order polynomial has *N* solutions:**

⇒ $\alpha_1, \alpha_2, \dots, \alpha_N$ (assume for now that α_i are distinct)

⇒ A_i 's are determined from initial conditions

⇒ **by cancelling common terms, get characteristic equation:**

$$a_N + a_{N-1} A \alpha + a_{N-2} A \alpha^2 + \dots + a_0 A \alpha^N = 0$$

⇒ **find roots of \nearrow , if all α_i are distinct, then**

$$g_n^{(h)} = A_1 \alpha_1^n + A_2 \alpha_2^n + \dots + A_N \alpha_N^n$$

⇒ **with α_1 as a multiple root of order k ,**

$$(A_{11}n^{k-1} + A_{12}n^{k-2} + \dots + A_{1k-1}n + A_{1k})\alpha_1^n$$

⇒ $g_n^{(p)}$ is determined by approp.-given from the form e_n

Example

$$6g_n - 5g_{n-1} + g_{n-2} = 6 \left(\frac{1}{5}\right)^n \quad n = 2, 3, 4, \dots \quad (*)$$

with $g_0 = 0, g_1 = \frac{6}{5}$

homogen.

sol.

$$\Rightarrow 6\alpha^2 - 5\alpha + 1 = 0 \quad (\text{char. eq.})$$

$$\Rightarrow \alpha_1 = \frac{1}{2} \quad \alpha_2 = \frac{1}{3}$$

$$\Rightarrow g_n^{(h)} = A_1 \left(\frac{1}{2}\right)^n + A_2 \left(\frac{1}{3}\right)^n$$

guess

$$\Rightarrow g_n^{(p)} = B \left(\frac{1}{5}\right)^n \Rightarrow \text{plug into } (*) \Rightarrow \text{get } B = 1$$

$$\Rightarrow g_n = g_n^{(h)} + g_n^{(p)} = A_1 \left(\frac{1}{2}\right)^n + A_2 \left(\frac{1}{3}\right)^n + \left(\frac{1}{5}\right)^n$$

using

init. cond.

$$\Rightarrow A_1 = 8, A_2 = -9$$

$$\Rightarrow g_n = \left(\frac{1}{2}\right)^{n-3} - \left(\frac{1}{3}\right)^{n-2} + \left(\frac{1}{5}\right)^n \quad n = 0, 1, 2, \dots$$



Use z-Transform

$$a_N g_{n-N} + a_{N-1} g_{n-N+1} + \cdots + a_0 g_n = e_n \quad n = k, k+1, \cdots$$

$$\text{def.} \Rightarrow G(z) = \sum_{n=0}^{\infty} g_n z^n$$

$$\Rightarrow \sum_{n=k}^{\infty} \sum_{i=0}^N \alpha_i g_{n-i} z^n = \sum_{n=k}^{\infty} e_n z^n$$

\Rightarrow carry out summations recognize $G(z)$,
 solve for $G(z)$ algebraically,
 then invert to get g_n



Example - Use z-Transform

(same) $6g_n - 5g_{n-1} + g_{n-2} = 6 \left(\frac{1}{5}\right)^n \quad n = 2, 3, 4, \dots$

$$\Rightarrow \sum_{n=2}^{\infty} 6g_n z^n - \sum_{n=2}^{\infty} 5g_{n-1} z^n + \sum_{n=2}^{\infty} g_{n-2} z^n = \sum_{n=2}^{\infty} 6 \left(\frac{1}{5}\right)^n z^n$$

$$\Rightarrow 6 \sum_{n=2}^{\infty} g_n z^n - 5z \sum_{n=2}^{\infty} g_{n-1} z^{n-1} + z^2 \sum_{n=2}^{\infty} g_{n-2} z^{n-2} = \sum_{n=2}^{\infty} 6 \left(\frac{1}{5}\right)^n z^n$$

$$\Rightarrow 6[G(z) - g_0 - g_1 z] - 5z[G(z) - g_0] + z^2 G(z) = \frac{6 \left(\frac{1}{5}\right)^n z^n}{1 - \left(\frac{1}{5}\right)^z}$$

$$\Rightarrow G(z) = \frac{6g_0 + 6g_1 z - 5g_0 z + \frac{\left(\frac{6}{25}\right)z^2}{1 - \left(\frac{1}{5}\right)z}}{6 - 5z + z^2}$$

$$\Rightarrow \text{using init. cond.: } (g_0 = 0, g_1 = \frac{6}{5})$$

$$G(z) = \left(\frac{1}{5}\right) \frac{z(6 - z)}{\left[1 - \left(\frac{1}{3}\right)z\right] \left[1 - \left(\frac{1}{2}\right)z\right] \left[1 - \left(\frac{1}{5}\right)z\right]}$$

Example - Use z-Transform (Cont...)

part. frac. exp. $\Rightarrow G(z) = \frac{-9}{1 - \left(\frac{1}{3}\right)z} + \frac{8}{1 - \left(\frac{1}{2}\right)z} + \frac{1}{1 - \left(\frac{1}{5}\right)z}$

$$\Rightarrow g_n = -9 \left(\frac{1}{3}\right)^n + 8 \left(\frac{1}{2}\right)^n + \left(\frac{1}{5}\right)^n \quad n = 0, 1, 2, \dots$$

Constant-Coeff. Linear Differential Equations

⇒ ***N*th order eq.:**

$$a_N \frac{d^N f(t)}{dt^N} + a_{N-1} \frac{d^{N-1} f(t)}{dt^{N-1}} + \cdots + a_1 \frac{df(t)}{dt} + a_0 f(t) = e(t)$$

⇒ **a_i 's are const., $e(t)$ is a given func.**

⇒ **also given N init. cond. (usually first N derivatives, usually at $t=0$).**

⇒ **find $f(t)$**

⇒ **have $f^{(h)}(t)$ and $f^{(p)}(t)$**

form

$$\Rightarrow f^{(h)}(t) = Ae^{\alpha t}$$

subst.

$$\Rightarrow a_N A \alpha^N e^{\alpha t} + a_{N-1} A \alpha^{N+1} e^{\alpha t} + \cdots + a_1 A \alpha e^{\alpha t} + a_0 A e^{\alpha t} = 0$$

⇒ **has N solutions which must solve char. eq:**

$$a_N \alpha^N + a_{N-1} \alpha^{N+1} + \cdots + a_1 \alpha + a_0 = 0$$

⇒ **if all α_i are distinct, then**

$$f^{(h)}(t) = A_1 e^{\alpha_1 t} + A_2 e^{\alpha_2 t} + \cdots + A_N e^{\alpha_N t}$$

where A_i 's are determined using init. cond.



Constant-Coeff. Linear Differential Equations (Cont...)

⇒ when have multiple root α_1 of order k , then have

$$(A_{11}t^{k-1} + A_{12}t^{k-2} + \cdots + A_{1k-1}t + A_{1k})e^{\alpha_1 t}$$

contribute in above form to homogeneous sol.

⇒ make a guess to find the particular sol. $f^{(p)}(t)$

complete

sol. ⇒ $f(t) = f^{(h)}(t) + f^{(p)}(t)$



Example

$$\frac{d^2 f(t)}{dt^2} - 6 \frac{df(t)}{dt} + 9f(t) = 2t \quad (*)$$

$$f(0^-) = 0 \quad \frac{df(0^-)}{dt} = 0 \quad (\text{init. cond.})$$

**homogen.
sol.**

\Rightarrow forming characteristic equation:

$$\alpha^2 - 6\alpha + 9 = 0$$

\Rightarrow find multiple root $\alpha_1 = \alpha_2 = 3$

\Rightarrow homogeneous sol. must be of the form

$$f^{(h)}(t) = (A_{11}t + A_{12})e^{3t}$$

\Rightarrow guess

$$f^{(p)}(t) = B_1 + B_2t$$

\Rightarrow substituting this back into (*) we get

$$B_1 = \frac{4}{27}, \quad B_2 = \frac{2}{9}$$

Example (Cont...)

complete sol. $\Rightarrow f(t) = (A_{11}t + A_{12})e^{3t} + \frac{4}{27} + \frac{2}{9}t$

using init. cond. $\Rightarrow A_{11} = \frac{2}{9}, \quad A_{12} = -\frac{4}{27}$

final sol. $\Rightarrow f(t) = \frac{2}{9} \left(t - \frac{2}{3} \right) e^{3t} + \frac{2}{9} \left(t + \frac{2}{3} \right) \quad t \geq 0$

Example - Using Laplace Transform Method

(using prev. example) $\frac{d^2 f(t)}{dt^2} - 6\frac{df(t)}{dt} + 9f(t) = 2t$

$$s^2 F^*(s) - sf(0^-) - f^{(1)}(0^-) - 6sF^*(s) + 6f(0^-) + 9F^*(s) = \frac{2}{s^2}$$

(using init. cond.'s, equal to 0, eliminate some terms above)

$$\Rightarrow F^*(s) = \frac{\frac{2}{s^2}}{s^2 - 6s + 9}$$

part. frac. exp. $\Rightarrow F^*(s) = \frac{\frac{2}{9}}{s^2} + \frac{\frac{4}{27}}{s} + \frac{\frac{2}{9}}{(s-3)^2} + \frac{-\frac{4}{27}}{s-3}$

inverting $\Rightarrow f(t) = \frac{2}{9}t + \frac{4}{27} + \frac{2}{9}te^{3t} - \frac{4}{27}e^{3t}$

(In queueing theory, sometimes need both, i.e., have differential-difference equations \Rightarrow then use both z and Laplace transforms).

Deriving Moments Via Transforms

Discrete time

z-Transform of a pmf p_k is given by $G_X(z) = \sum_k p_k z^k$

$$\Rightarrow \frac{\partial G_X(z)}{\partial z} = \sum_k k p_k z^{k-1}$$

$$\left. \frac{\partial G_X(z)}{\partial z} \right|_{z=1} = \sum_k k p_k = \bar{X} \quad \text{(Expectation)}$$

$$\Rightarrow \frac{\partial^2 G_X(z)}{\partial z^2} = \sum_k k(k-1) p_k z^{k-2}$$

$$\left. \frac{\partial^2 G_X(z)}{\partial z^2} \right|_{z=1} = \sum_k k(k-1) p_k = \overline{X^2} - \bar{X} \quad \text{(not quite variance, but can get it from this and the exp.)}$$

$\Rightarrow \vdots$

Deriving Moments Via Transforms (Cont...)

Continuous time

Laplace transform of a density func. $f(x)$ is $F^*(s) = \int_0^{\infty} e^{-sx} f(x) dx$

$$\Rightarrow \frac{d F^*(s)}{d s} = - \int_0^{\infty} e^{-sx} x f(x) dx$$

$$\left. \frac{d F^*(s)}{d s} \right|_{s=0} = - \bar{X}$$

$$\Rightarrow \left. \frac{d^2 F^*(s)}{d s^2} \right|_{s=0} = \bar{X}^2$$

$$\Rightarrow \vdots$$

HW: Compute first 2 moments of geometric and exponential distributions using transforms



Relationship of Transforms to Expectations

$$\Rightarrow f(t) \Leftrightarrow F^*(s) = \int_t e^{-st} f(t) dt = E[e^{-st}]$$

$$\Rightarrow p_X(k) \Leftrightarrow G(z) = \sum_k p_X(k) z^k = E[z^k]$$

Inequalities and Limit Theorems

- ⇒ May not be possible to determine distributions, but might be able to derive and use:
 - (a) moments
 - (b) inequalities and limits

Markov Inequality

⇒ **Simple Markov Inequality:**

⇒ If only know the expectation, provides a bound on probability distribution

⇒ For a r.v. X with mean μ , the Markov Inequality is:

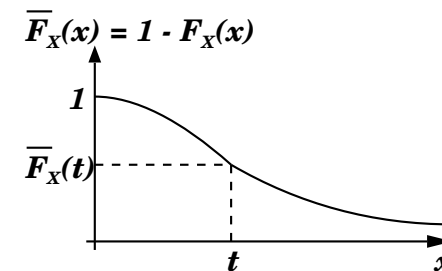
$$P[X \geq t] \leq \frac{\mu}{t}$$

→ assume X is a non-negative r.v.

Proof:

○ area under the curve

$$= \int_0^{\infty} \overline{F}_X(x) = E[X] = \mu$$



○ area of rectangle \leq area under the curve

$$\Rightarrow \overline{F}_X(t) \cdot t \leq E[X]$$

⇓

$$P[X \geq t] \cdot t \leq \mu \Rightarrow P[X \geq t] \leq \frac{\mu}{t}$$

Example

- Consider a system with MTTF of *100* hours
- Let X be a r.v. denoting the lifetime of a system
- By Markov Inequality:

$$P[X \geq t] \leq \frac{\mu}{t} = \frac{100}{t}$$

- Define reliability of a system as

$$R(t) \equiv P[X \geq t]$$

- Then

$$R(t) \leq \frac{100}{t}$$

⇒ To ensure system reliability more than *0.9*,
the system mission time $t < 111$.

Example (Cont...)

HW: How tight is the Markov bound for the exponential distribution with parameter

$$\lambda = \frac{1}{100}$$

Review Distribution

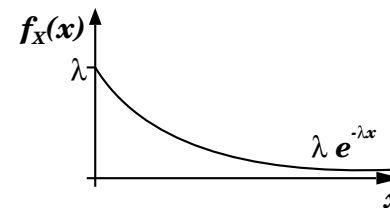
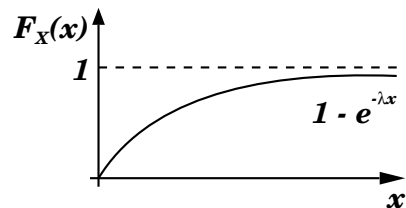
Exponential distribution:

$$P[X \leq x] = 1 - e^{-\lambda x} \quad x \geq 0$$

$$\Downarrow$$

$$F_X(x) = \begin{cases} 1 - e^{-\lambda x} & x \geq 0 \\ 0 & \text{otherwise} \end{cases}$$

$$f_X(x) = \frac{d F_X(x)}{d x} = \lambda e^{-\lambda x} \quad x \geq 0$$



Chebycher's Inequality

⇒ Assume we know μ and σ^2 of r.v. X , then for all $t > 0$,

$$P [|X - \mu| \geq t] \leq \frac{\sigma^2}{t^2}$$

Proof:

- let $Y = (X - \mu)^2 \Rightarrow Y$ is a non-negative r.v.
- applying Markov Inequality:

$$P [(X - \mu)^2 \geq t^2] \leq \frac{E [(X - \mu)^2]}{t^2} = \frac{\sigma^2}{t^2}$$

but

$$P [(X - \mu)^2 \geq t^2] = P [|X - \mu| \geq t]$$

Weak Law of Large Numbers

- ⇒ Let X_1, X_2, \dots, X_n be independent identically distributed r.v.'s with $E[X_i] = \mu$ and $Var[X_i] = Var[X] = \sigma_X^2 \quad \forall i$
- ⇒ Define arithmetic mean to be $\frac{X_1 + X_2 + \dots + X_n}{n}$

- ⇒ We would expect that for sufficient large n

$$\frac{\sum_{i=1}^n X_i}{n} \longrightarrow \mu$$

- ⇒ Let $S_n = \sum_{i=1}^n X_i$; consider r.v. $\frac{S_n}{n}$

$$\Rightarrow E\left[\frac{S_n}{n}\right] = \frac{n\mu}{n} = \mu$$

$$\Rightarrow Var\left[\frac{S_n}{n}\right] = \frac{1}{n^2} Var[S_n] = \frac{1}{n^2} n \sigma_X^2 = \frac{\sigma_X^2}{n}$$

$$\text{so, as } n \longrightarrow \infty \quad Var\left[\frac{S_n}{n}\right] \longrightarrow 0$$

Weak Law of Large Numbers (Cont...)

⇒ Applying Chebychev's Inequality to $\frac{S_n}{n}$, we get

$$P \left[\left| \frac{S_n}{n} - \mu \right| \geq \delta \right] \leq \frac{\sigma^2}{n \delta^2}$$

$$\Rightarrow P \left[\left| \frac{S_n}{n} - \mu \right| \geq \delta \right] \rightarrow 0 \text{ as } n \rightarrow \infty$$

⇒ the distribution of arithmetic mean $\frac{S_n}{n}$ becomes increasingly concentrated around the mean μ as n grows!

⇒ δ can be thought of as the error in approximating μ by the arithmetic mean

$$\lim_{n \rightarrow \infty} P \left[\left| \frac{S_n}{n} - \mu \right| \geq \delta \right] \rightarrow 0 \quad \leftarrow \text{weak law of large numbers}$$

or

$$\lim_{n \rightarrow \infty} P \left[\left| \frac{S_n}{n} - \mu \right| < \delta \right] \rightarrow 1$$

⇒ for any small δ , as n grows, the error will be less than δ with probability 1

Strong Law of Large Numbers

$$\Rightarrow \lim_{n \rightarrow \infty} \frac{S_n}{n} = E[X] = \mu \longrightarrow P \left[\lim_{n \rightarrow \infty} \left| \frac{S_n}{n} - E[X] \right| \geq \delta \right] = 0$$

or $\frac{S_n}{n} \xrightarrow{\text{a.s.}} E[X]$ as $n \rightarrow \infty$

Central Limit Theorem

$$Z_n = \frac{\sum_{i=1}^n X_i - n\bar{X}}{\sigma_X \sqrt{n}} \quad \text{where } X_i \text{ are i.i.d.}$$

with mean \bar{X} and variance σ_X^2

PDF of Z_n tends to the standard normal, i.e., x is real

$$P_{n \rightarrow \infty} [Z_n \leq x] = \phi(x) \quad \text{where} \quad \phi(x) \equiv \int_{-\infty}^x \frac{1}{\sqrt{2\pi}} e^{-\frac{y^2}{2}} dy$$

(Gaussian or normal distribution)